

# Curriculum vitae

## Personal data:

**Name:** Univ.-Prof. Mag. Dr. Thomas Schmickl  
**Date of birth:** 20.10.1969 in Graz (Austria)  
**Citizenship:** Austria  
**Family status:** married, 3 children



## Contact points:

<b>Personal homepage:</b>	<a href="https://www.thomasschmickl.eu">https://www.thomasschmickl.eu</a>
<b>Research Gate profile:</b>	<a href="https://www.researchgate.net/profile/Thomas-Schmickl">https://www.researchgate.net/profile/Thomas-Schmickl</a>
<b>Google scholar profile:</b>	<a href="https://scholar.google.com/citations?user=2kt2WucAAAAJ">https://scholar.google.com/citations?user=2kt2WucAAAAJ</a>
<b>ORCID profile:</b>	<a href="https://orcid.org/0000-0001-8598-7462">https://orcid.org/0000-0001-8598-7462</a>
<b>LOOP profile:</b>	<a href="https://loop.frontiersin.org/people/112419/overview">https://loop.frontiersin.org/people/112419/overview</a>
<b>Lab homepage:</b>	<a href="https://alife.uni-graz.at">https://alife.uni-graz.at</a>
<b>Lab Facebook:</b>	<a href="https://www.facebook.com/artificiallifelab">https://www.facebook.com/artificiallifelab</a>
<b>Lab Youtube:</b>	<a href="https://www.youtube.com/user/IZGartlife">https://www.youtube.com/user/IZGartlife</a>
<b>COLIBRI homepage</b>	<a href="https://colibri.uni-graz.at">https://colibri.uni-graz.at</a>
<b>University research portal page:</b>	<a href="https://online.uni-graz.at/kfu_online/wbforschungsportal.cbshowportal?pPersonNr=50874">https://online.uni-graz.at/kfu_online/wbforschungsportal.cbshowportal?pPersonNr=50874</a>
<b>Department website:</b>	<a href="https://biologie.uni-graz.at/en/metabolism-behavior-and-artificial-life/research/artificial-life/">https://biologie.uni-graz.at/en/metabolism-behavior-and-artificial-life/research/artificial-life/</a>

## Main Academic Trajectory:

**2012:** Habilitation “*The Collective Physiology of the Swarm: Modelling Self-Organization, Self-Regulation and Swarm-Intelligence of Distributed Systems in Biology and Bio-Robotics*”.

**1999 - June 2001:** Doctorate in Zoology at the University of Graz, Austria, passed with distinction. Ph.-D. thesis: “*Regulation of brood development in the honeybee (*Apis mellifera L.*): Feedback mechanisms and survival strategies of a superorganism*”.

**1989-1998:** Master of Biology (Zoology & Biochemistry) at the University of Salzburg, Austria, passed with distinction. Master thesis: “*Die Erfassung des mikrobiologischen Status in der Innenraumluft von Krankenanstalten*”.

***Positions:***

**Since Oct. 2016:** Full Professor at the Department for Zoology, Karl-Franzens-University Graz Austria, supervising three labs with a total head count of 40+ employees: The honeybee and wasp physiology lab, the animal behaviour lab and the Artificial Life Lab

**Since Jan 2019:** Founder and head of the research cluster “COLIBRI” (Complexity of Life in Basic Research and Innovation), a joint initiative of 22 professors and (and their associated workgroups) and 8+ Senior-PostDoc run groups at the university that join forces to intensify their research with focus on studying Complex Systems. This is the first step towards creating an “Institute for Complexity Research” at the University.

**Jan. 2013-Oct. 2016:** Associate Professor at the Department for Zoology, Karl-Franzens-University Graz, Austria, head of the Artificial Life Lab

**June 2012-Dec. 2012:** Professorship as “Basler Chair of Excellence” at the East-Tennessee State University (ETSU), in Johnson City, TN, U.S.A.

**Oct. 2007-June 2012:** Full-time assistant professor (faculty position) at the Department for Zoology, Karl-Franzens-University Graz, Austria, head of the Artificial Life Lab.

**Sept. 2007- Mar. 2013:** Lecturer at the University of Applied Sciences St. Pölten (Austria) in the course of studies “SimCom” (Computational Simulation, 1 month per semester).

**Jan. 2007 – Aug. 2007:** Visiting Professor at the East Tennessee State University (Johnson City, USA), Biological Department in the program SYMBIOSIS, granted by the Howard Hughes Medical Institute (8 months).

**Feb. 2006 - Feb. 2007:** Assistant Professor at the Department for Zoology, Karl-Franzens-University Graz (1 year).

**Mar. 2004 – Dec. 2006:** Lecturer at the Karl-Franzens-University Graz in the course of study “Biology” as side-duty of my university contract.

**Jan. 2004 – Feb. 2007:** Post-Doc-position in the EU-funded project “Intelligent Small World Autonomous Robots for Micro-manipulation” EU IST-FET-open project (IP) ‘I-SWARM’, no. 507006.

**Oct. 2003 – Dec. 2006:** Lecturer at the Karl-Franzens-University Graz in the course of study “Sciences of Environmental Systems”.

**Mar. 2003 – July 2006:** Lecturer at the University of Applied Sciences St. Pölten (Austria) in the course of studies “SimCom” (Computational Simulation).

**Mar. 2003 – Feb. 2004:** External lecturer at the Karl-Franzens-University Graz in the course of study “Biology”.

**Feb. 2003 – Jan. 2004:** Post-Doc-position in the FWF-funded (Austrian Science Foundation) project “Self-Organization of working bees on a honeybee comb: Investigating and modeling the spatial distribution, regulation of tasks, working effort, communication of colony state and sharing of a collective memory among working honeybees”, Project-Nr.: P 15961-B06.

**Sept. 2002 – Jan. 2003:** Lecturer at the University of Applied Sciences St. Pölten (Austria) in the course of studies “SimCom” (Computational Simulation), teaching Biological Modelling and Simulation, Self-Organization of Biological Systems and Swarm-Intelligence (4 months).

**Mar. 2002 – Jul. 2002:** External lecturer at the Karl-Franzens-University Graz in the course of study “Biology”.

**Aug. 2001 – Jan. 2002:** Scientific assistant (6 months) for studies of social insects (FWF-funded position).

**Feb. 2001 – Jul. 2001:** Guest professorship (6 months) at the Karl-Franzens-University Graz.

**Sept. 2000:** Programmer for developing a database application and a statistical analysis tool for corporate data at the company “Foto Schmickl” in Graz (1 month)

**Mar. 2000 – Mai 2000:** Guest professorship (3 months) at the Karl-Franzens-University Graz.

**1999:** “Contract for labour” (“Werkvertrag”) to program a literature database for the Department for Zoology, Graz.

**1998:** 1 year of “civil service” (instead of obligatory military service in Austria) at the Red Cross, Graz.

**1996 - 1997:** Software developer at the company "progressive software design" in Graz (15 months).

**1995:** Programmer for contract work at the company “grafomed” (Software Development) in Vienna (4 months)

**1994:** Employment as a member of the “production team” in a professional movie production of SATEL film for the Austrian Broadcasting Corporation (ORF, 2 months)

### ***Additional Scientific Qualifications:***

**2008:** 6 days of intensive training in “robot microcontroller programming” (with µC-compiler) and “micro-robot assembly” at Dr. Kornienko, at the Institute for Parallel and Distributed Systems (IPVS), Stuttgart, Germany. (18.1.-23.1. 2008)

**2006:** 5 days of intensive training in “robot microcontroller programming” (with µC-compiler) and “micro-robot assembly” at Dr. Kornienko, at the Institute for Parallel and Distributed Systems (IPVS), Stuttgart, Germany. (16.6.-20.6.06)

**2002:** Summer school at the European Forum Alpbach (Austria), granted by the “Club Alpbach Graz”. I applied to 2 courses: “Gaia-Theory: The earth as bio-geo-ecosystem” (by W. Wieser and S. Franck) and “Networks in Evolution” (by E. Szathmary and E. Jablonka).

**1999:** Study visit ("stage") at the "Unité de Génétique Moléculaire Bactérienne de l'Institut Pasteur", Paris.

**1998 – 2001:** Foundation of my project ‘e:doc’, an open-source, multi-platform front-end for LaTeX, written in Perl/Tk, which was well renown in the Linux community and in the Perl/Tk community.

**1998:** "Certificate of Excellence" from Microsoft as "Microsoft Certified Professional".

**1997:** "PC User" and "PC Administrator".

**1996:** "On-the-job training" in Delphi und Interbase by Borland International.

### ***Grants, awards, sponsorships and scholarships:***

**2024:** Our EU project RoboRoyale won the 6<sup>th</sup> Edge of Government Award in the category “Changing Perspectives” at the World Government Summit in Dubai. Awarded by the Prime Minister of the United Arab Emirates (UAE).

**2024-2029:** Grant acquisition and Principal Investigator (P.I.) of the project “SensorBees”. European Union EIC Pathfinder Open; total funding: € 3,197,502.50; individual contribution for Uni Graz: € 945,633.75; Grant Agreement ID: 101130325; 2024-2029.

**2023:** “Article of the year 2022” award by the journal “Complexity” for the article “Strong emergence arising from weak emergence”. <https://doi.org/10.1155/2022/9956885>

**2022:** Best symposium paper award at ICSA 2022 (International Conference for Structures and Architecture) for the article „A study model for reconstructing urban ecological niches“.

**2021:** “Prix Agathon de Potter de Biologie Animale” for the best nominated work in the year 2020 in the field of Zoology, awarded by the Royal Academy of Science, Letters and Fine Arts of Belgium.

**2021-2026:** Grant acquisition and Principal Investigator (P.I.) of the project “RoboRoyale”: European Union FET-PROACT (Excellent Science pillar) Horizon 2020; total funding: € 3,269,938.75; individual contribution for Uni Graz: € 1,170,786.25; Grant agreement ID: 964492

**2020:** Co-P.I. and co-coordinator (leading P.I. and coordinator: Dr. Ronald Thenius) of the EU funded FET project “ROBOCOENOSIS” (total funding is € 3.0 Mio, of which approx. 865 k€ are funding of the University of Graz). Grant agreement ID: 899520.

**2019:** The work of the EU project Hiveopolis, which is coordinated by me, was awarded the Distributed Design Award by Vienna Design Week and Maker Faire for the exhibition of the Hiveopolis smart beehive materials and prototypes at Vienna Maker Faire.

**2019-2024:** Grant acquisition, Project Coordinator (P.C.) and Principle Investigator (P.I.) of the project “HIVEOPOLIS”. European Union FET-PROACT (Excellent Science pillar) Horizon 2020; total funding: € 6,999,508.75; individual contribution for Uni Graz € 1,732,558.75; Grant agreement ID: 824069.

**2019-2020:** Grant acquisition and Principle Investigator (P.I.) of the project “Atempgrad”. European Union FET-LAUNCHPAD Horizon 2020; funding € 99,737.50; Grant agreement ID: 850877.

**2015-2019:** Grant acquisition and Project Coordinator (P.C.) and Principal Investigator (P.I.) of the project “subCULTron”. European Union FET-PROACT (Excellent Science pillar) Horizon 2020, total funding € 3,987,650.75; individual contribution for Uni Graz: € 901,300.00; Grant agreement ID: 640967.

**2018:** Teaching Award „Lehre: Ausgezeichnet!“ (“Teaching: Excellent!”) at the University of Graz, Austria (10/2018). This award is given to the lecturers of the best courses of the study year.

**2017:** Best paper award at IEEE SSCI Symposium on Artificial Life, Honolulu, USA (12/2017) for the article “Governing the swarm: Controlling a bio-hybrid society of bees & robots with computational feedback loops”.

**2017:** Best paper award at the 10th EAI International Conference on Bio-inspired Information and Communications Technologies (BICT), New Jersey, USA (03/2017) for the article “Robotic oligarchy: how a few members can control their whole society by doing almost nothing”.

**2015-2019:** Grant acquisition and Principal Investigator (P.I.) in the project “Flora Robotica”: European Union FET-PROACT (Excellent Science pillar) Horizon 2020; total funding: € 3,641,782.50; individual contribution for Uni Graz: € 608,445.--; project-no. 640959.

**2015:** Grant acquisition and Supervisor in the small-scale, small-term project “vibration experiments”, funded by the FFG with € 1,000.-- in the funding program “young talents”.

**2015:** Grant acquisition and Supervisor in the small-scale, small-term project “robotic experiments 4”, funded by the FFG with € 1,000.-- in the funding program “young talents”.

**2014:** Grant acquisition and Supervisor in the small-scale, small-term project “robotic experiments 3”, funded by the FFG with € 1,000.-- in the funding program “young talents”.

**2013:** Grant acquisition and Supervisor in the small-scale, small-term project “shoaling behaviour”, funded by the FFG with € 1,000.-- in the funding program “young talents”.

**2013:** Grant acquisition and Supervisor in the small-scale, small-term project “temperature organ”, funded by the FFG with € 1,000.-- in the funding program “young talents”.

**2013:** Grant acquisition and Supervisor in the small-scale, small-term project “wall following behaviour”, funded by the FFG with € 1,000.-- in the funding program “young talents”.

**2013-2018:** Grant acquisition and Project Coordinator (P.C.) and Principal Investigator (P.I.) of the project “ASSISI\_bf”. European Union FP7-IP (FET); total funding € 7,649,939.--; individual contribution for Uni Graz: € 2,166,280.--; project-no. 601074. Finished with the final assessment “excellent” by the reviewer panel.

**2014:** Science-Award by the Government of the State of Styria 2013 in “Simulation & Modeling” in the subject “Basic research”.

**2012:** Grant acquisition and Supervisor in the small-scale, small-term project “robotic experiments 2”, funded by the FFG with € 1,000.-- in the funding program “young talents”.

**2012:** Grant acquisition and Supervisor in the small-scale, small-term project “behavioural analysis – part 2”, funded by the FFG with € 1,000.-- in the funding program “young talents”.

**2012:** Grant acquisition and Supervisor in the small-scale, small-term project “behavioural analysis – part 1”, funded by the FFG with € 1,000.-- in the funding program “young talents”.

**2012-2014:** Grant acquisition and Principal investigator of the FWF-funded project REBODIMENT (funding € 270,500.--), project-no. P23943-N13

**2012:** Mentoring award from the Ministry of Transport, Innovation and Technology (Ms. Doris Bures) for the FFG funded small-scale project “young talents” with the mentored student T. Kunzfeld.

**2012:** Visiting-professorship as “Chair of Excellence for the Integration of the Arts, Rhetoric, and Science” at the East-Tennessee State University (ETSU), in Johnson City, TN, USA (6.5 months, funded US-\$ 65.800,-- by the Wayne G. Basler foundation)

**2011:** Grant acquisition and Supervisor in the small-scale, small-term project “robot experiments”, funded by the FFG with € 1,000.-- in the funding program “young talents”.

**2011-2014:** Grant acquisition and Project Coordinator (P.C.) and Principal Investigator (P.I.) of the project “CoCoRo”. European Union FP7-ICT; total funding: € 3 755 902,00; individual funding for Uni Graz: € 810,420.--; project-no. 270382. Finished with the final assessment “excellent” by the reviewer panel.

**2010:** Grant for Initiation financing for the proposal to the EU project CoCoRo. Funded with € 7.500,-- by the 'FFG: Forschungsförderungsgesellschaft', Austria.

**2009-2013:** Grant acquisition for front-end financing ('Zusatzfinanzierung') for the EU-FP7 project "Symbrion" - Symbiotic Evolutionary Robot Organisms. Funded with € 38.700,00 by the 'Bundesministerium für Wissenschaft und Forschung', Austria.

**2009-2013:** Grant acquisition for front-end financing ('Zusatzfinanzierung') for the EU-FP7 project "Replicator". Funded with € 49.106,70 by the 'Bundesministerium für Wissenschaft und Forschung', Austria.

**2009:** Grant for initiation financing for the proposal to the EU project MEDUSAS. Funded with € 15.000,-- by the 'FFG: Forschungsförderungsgesellschaft', Austria.

**2008-2013:** Grant acquisition and Principal Investigator (P.I.) of the project “Symbrion”: European Union FP7-ICT (FET); total funding € 7,452,801.--; individual funding for Uni Graz: € 536,000.--; project-no. 216342.

**2008-2012:** Grant acquisition and Principal Investigator (P.I.) of the project “Replicator”: European Union FP7-ICT; total funding € 7,056,633.--; individual funding for Uni Graz: € 632,040.--; project-no. 216240.

**2007-2010:** Grant acquisition and Principal Investigator (P.I.) of the FWF-project “Temperature-induced aggregation of young honeybees: Individual behaviour vs. collective behaviour” (funded € 170.000,-- by the Austrian Science Foundation).

**2007:** “Visiting Professor” at the East Tennessee State University (8 months, funded US-\$ 30.800,-- by the program SYMBIOSIS, granted by the Howard Hughes Medical Institute).

**2006:** Granted € 3600,-- from the museum “Haus der Wissenschaften” to establish a robotic swarm installation.

**2003:** Scholarship for visiting the “European Forum Alpbach 2003” granted by the “IV” (“Industry Association of Austria”).

**2002:** Scholarship for visiting the “European Forum Alpbach 2002” granted by the “IV” (“Industry Association of Austria”).

**2001:** 6 month guest professorship (topic: bioinformatics, biomodelling) at the Karl-Franzens-University Graz (funded € 24.000,-- by the University of Graz).

**2000:** 3 month guest-professorship (topic: bioinformatics, biomodelling) at the Karl-Franzens-University Graz (funded € 12.000,-- by the University of Graz).

**1999:** Travel scholarship for presentation at the “APIMONDIA conference” in Vancouver, Canada, granted by the Major of Graz, Austria.

**1999:** Travel scholarship for presentation at the “APIMONDIA conference” in Vancouver, Canada, granted by the Styrian Governor.

**1985:** Awarded by the “Silver Diploma” for excellent results in the “Akademisches Gymnasium”, Graz, by the Styrian Governor.

### ***Breaks in education:***

**1999-2000:** One year of “paternity leave”.

**1998-1999:** One year of civil services at the Austrian “Red Cross” (obligatory in Austria).

### ***Reviewing:***

I review articles for the following journals and books/scientific series:

<ul style="list-style-type: none"><li>▲ ACM Transactions on Autonomous and Adaptive Systems</li><li>▲ Acta Biotheoretica</li><li>▲ Adaptive Behavior</li><li>▲ Advances in Complex Systems</li><li>▲ Apiacta</li><li>▲ Apidologie</li><li>▲ Artificial Life</li><li>▲ Artificial Intelligence</li><li>▲ Bulletin of Mathematical Biology</li><li>▲ Ecological Modelling</li><li>▲ Engineering Applications of Artificial Intelligence</li><li>▲ Genetic Programming and Evolvable Machines</li></ul>	<ul style="list-style-type: none"><li>▲ Mathematical and Computer Modelling of Dynamical Systems</li><li>▲ Nature Physics</li><li>▲ Naturwissenschaften</li><li>▲ Neural Computing and Applications</li><li>▲ PLOS One</li><li>▲ Proceedings of the Royal Society B</li><li>▲ Proceedings of the Royal Society Interface</li><li>▲ Robotica</li><li>▲ Robotics</li><li>▲ Science</li><li>▲ Science Robotics</li><li>▲ Scientific Reports</li><li>▲ Springer Swarm Intelligence</li></ul>
--	--

<ul style="list-style-type: none"> <li>▫ IEEE Transactions on Robotics</li> <li>▫ Insectes Sociaux</li> <li>▫ Insect Science</li> <li>▫ Intelligent Service Robotics</li> <li>▫ International Journal of Innovative Computing and Applications</li> <li>▫ Journal of Economic Entomology</li> <li>▫ Journal of Insect Behavior</li> <li>▫ Journal of Theoretical Biology</li> </ul>	<ul style="list-style-type: none"> <li>▫ Springer book “Symbiotic multi-robot organisms” (eds. Dr. S. Kernbach, Prof. P. Levi)</li> <li>▫ Theoretical Biology</li> <li>▫ Theoretical Population Biology</li> <li>▫ Transactions on Evolutionary Computation</li> <li>▫ Transactions on Robotics</li> </ul>
---	--

I act in program committees & scientific boards of conferences on a frequent basis:

<ul style="list-style-type: none"> <li>▫ ACVRW 2020</li> <li>▫ ALIA 2016</li> <li>▫ ALIFE (always)</li> <li>▫ ANTS (always)</li> <li>▫ ARW 2012</li> <li>▫ AWARE 2011</li> <li>▫ BICT (always)</li> <li>▫ BIONETICS</li> <li>▫ BIOROB 2012</li> <li>▫ CCS 2019</li> <li>▫ CoSMoS 2015</li> <li>▫ CSI 2017</li> <li>▫ DARS (often)</li> <li>▫ EAIS 2017</li> <li>▫ ECAI (often)</li> <li>▫ ECTA (always)</li> <li>▫ ECAL (always)</li> <li>▫ EURBEE 2008</li> <li>▫ EvoApps (always)</li> <li>▫ EvoRobot (often)</li> </ul>	<ul style="list-style-type: none"> <li>▫ EvoStar (often)</li> <li>▫ FAS 2018</li> <li>▫ GECCO (always)</li> <li>▫ GCAI 2017</li> <li>▫ ICARIS 2010</li> <li>▫ ICRA 2016</li> <li>▫ IEE CEC 2009</li> <li>▫ IEEE CIS 2017</li> <li>▫ IEEE ALIFE (often)</li> <li>▫ IEEE SSCI (often)</li> <li>▫ IROS (multiple times)</li> <li>▫ LIAR 2017</li> <li>▫ Living Machines (always)</li> <li>▫ MATHMOD (often)</li> <li>▫ MESROB 2016</li> <li>▫ PRIMA 2015</li> <li>▫ SASO (often)</li> <li>▫ SWARMFEST 2017</li> <li>▫ TAROS (often)</li> <li>▫ TEVC 2013</li> </ul>
--	--

## European-level reviewing and consulting:

**2019:** Reviewer of the EU FET-Open project PHOENIX at the yearly review meeting of the project in Eindhoven, Netherlands

**2018:** Reviewer of the EU FET-Open project PHOENIX at the yearly review meeting of the project in Eindhoven, Netherlands

**2016:** Evaluator for EU grant proposals in the call FET PROACTIVE: emerging themes and communities

**2011:** Reviewer for grant proposals for the Swiss National Science Foundation (SNSF)

**2011:** Advisory board of AWARENESS, an EU-funded Coordination Action (FP7)

**2011:** Member of the consultation board in the EU-FET-Proactive consultation "Living technologies", 10.11.2011, invitation by Dargmar Floeck. Leading to the calls FOCAS and ELEVIT

**2011:** Reviewer for the call FP7-ENV-2011-2.1.4-2 "Behaviour of ecosystems, thresholds and tipping points"

**2011:** Reviewer for the call FP7-ICT-2011-7 – ICT – Information and Communication Technologies - "Cognitive Systems and Robotics"

**2011:** Consultation of Rothamsted Research & SYNGENTA in the UK-national project "Honeybee population dynamics: Integrating the effects of factors within the hive and in the landscape" on honeybee population modelling and honeybee behavioural modelling (2.11.2011, Bracknell, UK)

**2010:** Consultant at the workshop "EVOBODY - New Principles of Unbound Embodied Evolution" in Malta, 23<sup>rd</sup> Sept. 2010.

**2009:** Consultant at the EU FET proactive external consultation workshop "Fundamentals of collective adaptive systems". 3.-4. November 2009, Leuven, Belgium.

### ***Organizing summer/winter schools or similar activities:***

**2024:** Hiveopolis Winter School "Winter School on Modelling and measuring Biohybrid Multi-Level Complex Systems". 20<sup>th</sup> to 23<sup>rd</sup> of February 2024, in Graz. Organized in cooperation with Arqus, COLIBRI, and the EU projects RoboRoyale and Watchplant.

**2022:** Co-organizing the COLIBRI track in the combined Hackathon "Change" and the "Brain, Behavior & Society" Springschool at the University of Graz, 8<sup>th</sup> of April.

**2021:** Organizing the track "Bio-inspired & Bio-mimetic Algorithms" at the "Virtual Vehicle Summer School 2021 – Beyond A.I." in Graz, 13.-15.9.2021 together with TU Graz and the Virtual Vehicle cluster.

**2017:** Assisi\_bf Summer School 2017 - "Engineering and Evolution of Bio-Hybrid Societies", Graz, Austria 29<sup>th</sup> – 31<sup>th</sup> - August 2017, at the Karl-Franzens-Universität Graz Organizer: Thomas Schmickl & Martina Szopek

**2016:** Assisi\_bf Winter School 2016 - "From bio-inspired to bio-hybrid (robotic) systems", Lausanne, Switzerland 12<sup>th</sup> – 14<sup>th</sup> January 2016, at the Ecole Polytechnique Fédérale de Lausanne Organizer: Francesco Mondada & Thomas Schmickl

***Organization & co-organization of scientific symposiums and meetings:***

**2024:** Symposium “Biohybrids through Organism-Technology-Interactions – Models, Methods, Potentials, Epistemology & Ethics” as a COLIBRI Focus Workshop. 18<sup>th</sup>-19<sup>th</sup> of February 2024 in Graz.

**2023:** Symposium “Bioinspired Engineering, Soft Robotics and Bio-Hybrid Technologies as New Frontiers in Sustainable Agriculture and Environmental Management” at the 2023 IEEE International Workshop on Metrology for Agriculture and Forestry (MetroAgriFor 2023), together with Dr. Donato Romano.

**2022:** Special Session “Workshop on Animal-Robot Interaction” at the 2022 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2022) in Kyoto, Japan, October 23<sup>rd</sup> to Oct 27<sup>th</sup>, together with Dr. Donato Romano and Prof. Cesare Stefanini.

**2021:** Special Session “Complexity ALI[F|V]E: Socializing & Eco-integrating robots with living organisms” at the ALIFE 2021 Konference in Prague, Czech Republic. Organized together with Dr. Donato Romano, Dr. Ronald Thenius and Prof. Martin Grube.

**2015:** Workshop “Bioinspired Underwater Robotics” 2015, Hamburg, Germany, 02<sup>nd</sup> October 2015 at IROS 2015 Organizer: Cesare Stefanini & Thomas Schmickl

**2015:** Symposium “Social Behaviour and Self-Regulation in Insects, Swarms and Algorithms” 2015, Graz, Austria, 08<sup>th</sup> September 2015 at DZG Organizer: Thomas Schmickl & Martina Szopek.

**2014:** Symposium “Emergent social behaviours in bio-hybrid systems” at Living Machines 2014, Milano, Italy, 30th July – 1st August 2014 with Stuart Wilson & Jose Halloy

**2013:** Symposium “Emergent social behaviours in bio-hybrid systems” at Living Machines 2013, London, UK, 29th July - 2rd August 2013 with Stuart Wilson & Jose Halloy

**2012:** Symposium “Honeybee colony organization: from empirical studies to modeling approaches and technical applications” at the EURBEE 2012 (together with Dr. Matthias Becher)

**2011:** Special Session “Self-adaptive and self-aware multi-component systems” at BIONETICS 2011 (together with Dr. Ronald Thenius)

**2009:** Workshop “Agent connectivity: the role of cooperation in the regulation of the behavior of animals and robots” at ECAL 2009, Budapest, 13<sup>th</sup> - 16<sup>th</sup> September 2009. Organized together with Prof. Istvan Karsai, ETSU, USA.

**2009:** Symposium “Modeling the swarm” at MATHMOD 2009, Vienna 11<sup>th</sup> -13<sup>th</sup> February. Organized together with Dr. Heiko Hamann, University of Karlsruhe.

**2005:** Co-Organizing the symposium “Optimization and regulation of work in social insects” on the Third European Congress on Social Insects (IUSSI), St. Petersburg State University, 22<sup>nd</sup> to 27<sup>th</sup> of August 2005.

**2005:** "I-SWARM"-workshop at the EURON conference, February 16<sup>th</sup> - 18<sup>th</sup> 2005; Warszaw, Poland.

**2004:** Workshop “Modeling of biological swarms”. Participants: Scientists from universities in: Stuttgart (D), Karlsruhe (D), St. Ingbert (D), Lausanne (CH), Sheffield (UK), Kanpur (India) and Pisa (I), on May 7<sup>th</sup>, 2004, Graz, Austria.

### ***Invited talks/Plenary lectures/Keynotes:***

**2024:** “Digital technology as a contingency for ecosystem decay”, at the Helex Annual Meeting 2024, Graz, Austria, 15<sup>th</sup> of October 2024, invitation by the organizing team.

**2024:** “Strong Emergence Arising from Weak Emergence”, Complexity of Life Conference 2024, Graz. 24. September 2024, invitation by the organizing team.

**2024:** “Biohybrid Honeybee Hives for Research and Application”, Workshop “Nature Unleashed” at 2024 10th IEEE RAS/EMBS International Conference for Biomedical Robotics and Biomechatronics (BioRob), Heidelberg, Germany, 1<sup>st</sup> September 2024, invitation by Gianluca Manduca and Cesare Stefanini

**2024:** “Studying Complex Honeybee Behaviours with the Help of Robots”. Robosoft 2024, San Diego, USA. 14<sup>th</sup> of April 2024 in the symposium “Bio-Hybrids: When Robots Come Alive”, invitation by Prof. Miriam Filippi, ETH Zurich, CH.

**2024:** “Robotics as an Eco-Effective Contingency for Weakened Ecosystems?” 11<sup>th</sup> of April 2024, invitation by Prof. Wi-Min Shen, University of Southern California, Los Angeles, USA.

**2024:** “Can Robots Save Nature? How Robotics, AI, and Big Data can be a Contingency for Decaying Ecosystems”. 8<sup>th</sup> of April, 2024, invitation by Prof. John Long, Vassar College, Poughkeepsie, NY, USA.

**2024:** “Eco-Effective Robotics: A Contingency for Ecosystem Decay?” 4th of April 2024, invitation by Prof. Maurizio Porfiri, Tandon School of Engineering, NYU, Brooklin, NY, USA.

**2024:** “Bio-hybrid robotic systems: A contingency for ecosystem decay?”. COLIBRI Focus Wokshop “BIOHYBRIDS THROUGH ORGANISM-TECHNOLOGY- INTERACTIONS – Models, Methods, Potentials, Epistemology & Ethics. 18<sup>th</sup> February 2024.

**2023:** Live (streamed) presentation of the Hiveopolis technology (prototypes) at the BioBienenApfel Event, 30<sup>th</sup> of March in Vienna, Austria, to international media and selected guests: Sebastian Vettel, Othmar Karas, Elina Garanca, Dominic Thiem, Andreas Gabalier, Franco Foda, Elisabeth Görgl, Mario Barth, Lisa-Marie Schiffner, Karl & Katrin Hohensinner et al. Invitation by Frutura, Austria through Dr. Philipp Berkessy.

**2022:** Live (streamed) presentation of the Hiveopolis technology (prototypes) at the BioBienenApfel Kickoff Event in Munich, 14<sup>th</sup> of May in Munich to international media and selected guests: Sebastian Vettel, Othmar Karas, Andreas Gabalier, Franco Foda, Charlott Cordes, Elisabeth Görgl, Andreas Döllerer, Lisa-Marie Schiffner, Karl & Katrin Hohensinner et al. Invitation by Frutura, Austria through Dr. Philipp Berkessy.

**2022:** “Embedded technology can modulate collective decision making in natural swarm organisms”. Invited Talk at the symposium “The Digital Future of Bees” at the University of Limerick, 4<sup>th</sup> of March.

**2021:** "Liquid brains, before 'liquid brain' was a thing". Invited talk (invitation by Prof. Dr. Bernat Corominas-Murtra) as part of the PhD seminar of the "Complexity of Life" Doctoral Academy at the University of Graz, Austria on December 17.

**2021:** "Bio-inspirierte & bio-hybride Technologie zur Stabilisierung geschädigter Ökosysteme". Invited talk (invition by Prof. Dr. Robert Felfe) as part of the the AVL-Ringvorlesung "Kulturthema: TIERE - Bestien, Verwandte, kulturelle Akteure?" at the Zentrum für Kulturwissenschaften, University of Graz, Austria on December 13.

**2021:** Panel discussion at the Virtual Vehicle "Beyond AI" summer school in Graz, Austria on September 15.

**2021:** „Natural & robotic swarms: Applying technology to modulate collective decision making in natural and bio-hybrid systems.“ Invited talk at the pre-COP26 conference (Italy, Ministry of the Environment). Invitation by Prof. Cesare Stefanini, Scuola Superiore Sant’Anna, Pontedera, Italy

**2021:** Keynote talk „Fixing Broken Ecosystems with Autonomous Robot Swarms.“ Invited talk at SCIFI-IT 2021, Science Fiction Prototyping Conference at the University of Leuven, Ghent Research Centre in Ghent, Belgium from April 14-16, 2021 on invitation by Dr. Philippe Geril (Ghent, Belgium)

**2021:** „Proactive Monitoring & Ecosystem Hacking: The Role of Robots in the Ongoing Ecosystem Crisis.“ (Purdue University, USA) Invited seminar talk in an online-course about bio-hybrid systems. 2.2.2021, invitation by Prof. Jason Parry, Purdue University, USA

**2020:** "From Proactive Monitoring to Ecosystem Hacking: The Role of Robots in the Ongoing Ecosystem Crisis" at IROS 2020, 22nd-29th of October 2020, IEEE/RSJ IROS Conference LAS VEGA (USA) in the Workshop on animal & robot interaction, invitation by Donato Romano & Cesare Stefanini)

**2020:** "Ökologische Nachhaltigkeit: Wie kann moderne Technik zum Schutz der Umwelt einsetzen?". In lecture series "Was ist Nachhaltigkeit?", 14th Oct. 2020, invitation by Mag. Dr. Christian Kozina, RCE Graz-Styria - Zentrum für nachhaltige Gesellschaftstransformation, Karl-Franzens-Universität Graz.

**2020:** Podium discussion "Nachhaltige Entwicklung, 14th Oct. 2020, invitation by Mag. Dr. Christian Kozina, RCE Graz-Styria - Zentrum für nachhaltige Gesellschaftstransformation, Karl-Franzens-Universität Graz.

**2020:** Public interview at the Future Tech Week (EU - EIC) 21.-25. Sept. 2020 (Interview with Erich Prem, FET-EU)

**2020:** Public video presentation Hiveopolis at the Future Tech Week (EU - EIC) 21.-25. Sept. 2020

**2020:** GreentechCluster Innovators Club Keynote "Autonome Roboter für Umwelt-Monitoring und Interventionen", 6<sup>th</sup> oct. 2020, invitation by Johann Koinegg, Green Tech Cluster Styria GmbH, held online due to Covid19 pandemic.

**2020:** "Robot Swarms for Repairing Broken Ecosystems" at the Fakultätskolloquium of the Faculty for Computer Science, Electrical Engineering and Mathematics, Invitation by Prof. Holger Karl und Prof. Markus Holt.

**2019:** „Repairing broken Ecosystems with autonomous robot swarms“ at NJIT, Newark, New Jersey, USA, invitation by Prof. Simon Garnier (Federated Department of Biological Sciences)

**2019:** „Repairing broken Ecosystems with autonomous robot swarms“ at NYU - Tandon School of Engineering, Brooklyn, New York, USA, invitation by Prof. Giuseppe Loianno (RiskEconLab, Courant Institute of Mathematics)

**2019:** “Artificial Life: approaching the core” at Binghamton University, Binghamton, New York, USA, invitation by Prof. Hiroki Sayama (System Science and Industrial Engineering)

**2019:** „Repairing broken Ecosystems with autonomous robot swarms“ at Binghamton University, Binghamton, New York, USA, invitation by Prof. Hiroki Sayama (System Science and Industrial Engineering)

**2019:** Invited talk at the International Conference at the University of Graz, “Questioning the Non-Human Other Political Potentials of Living Beings in Art” (17.-19.10.2019): “Repairing broken ecosystems with robotic surrogates”, invited by Sabine Flach, Institut für Kunstgeschichte, Graz, Österreich

**2019:** Invited talk at the EU European Innovation Days (24. – 26.09.2019): “Will Robots save Nature? How autonomous robotic agents can help us to prevent the current ecological collapse”, invited by the EU, Brussels Belgium

**2019:** Invited plenary talk at Vienna Design Week 2019: “Technological Augmentation of Ecosystems for a Sustainable Biosphere”. Invitation by Vienna Design Office.

**2019:** Invited talk at the International Symposium, Exhibitions and Workshop (20.-21.06.2019): “Earth without Humans, Repairing Broken Ecosystems with Robotic Surrogates”, invited by Kapelica Gallery and Artificial Life Symposium, Ljubljana, Slovenia

**2019:** Invited talk at the “AEC Eröffnungsfeier Linz” (15.-16.06.2019): “Symbiotische Berechnung von Bio-Hybridsystemen” invited by the Ars Electronica Linz, Linz, Austria

**2019:** Invited talk at the Sustainability4U Ringvorlesung 2019 (20.03.2019): “Können Roboter die Natur retten? Der Beitrag automomer Roboter (-Schwärme) zur Beobachtung und Reparatur bedrohter Ökosysteme“, invited by Sustainability4U, Graz, Österreich

**2018:** Invited talk at the workshop: "SCIENTIĆ & ROBOTICA" (05. – 08. September 2018), “Robotiere, kybernetische Pflanzen und gemischte Gesellschaften”, invited by EPFL Francesco Mondada, Lausanne, Schweiz

**2018:** Invited talk at the conference: ICTP International Centre for Theoretical Physics (07.-11. May 2018): “Mathematical Modeling of Collective Deception and the Emergence of Fundamentalism”, invited by ICTP committee, Triest, Italy

**2018:** Invited talk on the Research Seminar in Economics (09.01.2018): Artificial Life in Graz: Collective Decision in Animals and Robots invited by Christoph Kuzmics, Universität Graz

**2017:** Invited talk at the Round table organized by AVL List GmbH and the University of Graz presenting the technical developments researched at the Artificial Life Lab Graz.

**2017:** Invited talk at the Akademie Graz, “swarming and networking” (23.08.2017): “Lecture on Artificial Life”, invited by Akademie Graz, Österreich

**2017:** Summer School ASSISIbf (Graz, Austria, 29.-31.08.2019): “From Honey bees to bio-hybrid robot swarms”, opening lecture (29<sup>th</sup> August 2017)

**2017:** Invited talk at the Lakeside Research Days 2017: Self-Organization and Swarm Intelligence in Cyber Physical Systems (10.-12. July 2017): “Bio-inspired swarm robotics: From honeybees to space exploration”, invited by Wilfried Elmenreich, Professor of Smart Grids, Institute of Networked and Embedded Systems, Alpen-Adria-Universität Klagenfurt

**2017:** Invited talk at the conference: IVth International Conference on Research and Education (Poznan, Poland, 06.-08. April 2017): “Robots and honeybees: decoding smart swarms”, invited by Dr hab. Agnieszka Ludwików, Adam Mickiewicz University in Poznań

**2017:** Invited talk at the workshop: “Annäherung an die Natur. Zum Einsatz von Computersimulationen in der Bionik”, (Lüneburg, Deutschland, 30.01.-01.02.2017): “Animal and Robot Societies Self-Organise and Integrate by Social Interaction (Bees and Fish)”, invited by Dr. Jan Müggenburg Leuphana University Lüneburg

**2016:** Invited talk to the Podiumsdiskussion ARS ELECTRONICA (Linz, Austria, 08.-12.09.2016) “Künstliche Intelligenz und Algorithmen”, invited by Ars Electronica, Linz, Austria)

**2016:** Invited lecture at the conference: CAMS 2016, 10<sup>th</sup> IFAC Conference on Control Applications in Marine Systems (Trondheim, Norwegen, 13.-16. September 2016): “Subcultron - a New Approach to Long-Term Underwater Autonomy”, invited by PhD Adjunct Associate Professor Vahid Hassani NTNU, Norway

**2016:** Invited talk at Workshop „Berechnete Tiere. Technik und Verdatung in den Human-Animal-Studies“ (Bochum, Deutschland, 22<sup>nd</sup> April 2016): “Biohybrid systems - Tiere, Pflanzen, Roboter, Agenten und Algorithmen”, invited by Prof. Stefan Rieger

**2016:** Invited lecture at winter school of projekt ASSISIbf (Lausanne, Switzerland, 12<sup>th</sup> Jan. 2016): “Honeybee Biology: Collective Behaviors”, Opening plenary lecture, invited by Prof. Francesco Montada at EPFL Lausanne, CH.

**2016:** Invited lecture at EPFL (Lausanne CH, 13<sup>th</sup> Jan. 2016): “From CoCoRo to subCULTron: Collective Cognition in Autonomous Underwater Robot Swarms”, invited by Prof. Alcherio Martinoli

**2015:** IROS 2015 (Hamburg, Germany, 2<sup>th</sup> Oct 2015): “Modular bio-inspired algorithms for autonomous underwater robot swarms in CoCoRo and subCULTron” in the workshop “Bioinspired underwater robotics” invited by Prof. Cesare Stefanini.

**2015:** DZG 2015 (Graz, Austria, 8<sup>th</sup> Sept. 2015): “Honeybee-inspired models and swarm (robotic) algorithms” in the workshop “Social Behaviour and Self-Regulation in Insects, Swarms and Algorithms”.

**2015:** EMRA 2015 (Lissabon, Portugal, 18<sup>th</sup> – 19<sup>th</sup> June 2015): “subCULTron – Approaching the next level”, invited by Prof. Nikola Miskovic, University of Zagreb

**2015:** Montagsakademie der Uni Graz (Graz, Österreich, 04.05.2015): *Soziale Cyborgs : Maschinen und Lebewesen verschmelzen zu Super-Gesellschaften.* Invitation by Prof. Alfred Posch

**2015:** subCULTron. Workshop “*European Robotics projects: Beyond the Robotics Unit*”, 11<sup>th</sup> March 2015, European Robotics Forum 2015, Vienna. Invitation by Anne Bajart, Olivier Da Costa, Cécile Huet – European Commission.

**2015:** Collective Cognitive Robotics (CoCoRo). Workshop “*Step change results from FP7 projects*”, 12<sup>th</sup> March 2015, European Robotics Forum 2015, Vienna. Invitation by Cécile Huet , Bjoern Juretzki , Franco Mastroddi – European Commission.

**2015:** Research overview of the Artificial Life Lab, Graz. At: KNAPP A.G., 6<sup>th</sup> March 2015. Invitation by Mag. Andreas Miller.

**2015:** Closing the loop between honeybees & robots in collective decision. At INDP Workshop „Social Insect Behaviour“ at Champalimaud Foundation, Lisbon, Portugal, 26th – 29th Jan. 2015. Invitation by Carolina Doran, Simone Lackner, Eugenia Chiappe, Gonzalo G. de Polavieja.

**2014:** Invited talk on” Schwarmintelligenz-Algorithmen” at Knapp AG, Invitation by Mag. Andreas Miller.

**2014:** Collective behaviors in honeybees: from observation to modeling to re-embodiment to bio-hybrid systems. Seminar at Université libre de Bruxelles (ULB). 17<sup>th</sup> Dec. 2014. Invitation by Prof. Jean-Louis Deneubourg.

**2014:** Der Bot im Schwarm: Wie Roboter und Gesellschaften zu einem völlig neuen homogenen Ganzen verschmelzen. TEDxGRAZ talk, 12th Nov. 2014. Invitation by Friso Schopper. <https://www.youtube.com/watch?v=eS4dyznbdnc>

**2014:** Social Adaptation of Robots for Modulating Self-Organization in Animal Societies. FOCAS workshop at the SASO 2014 Conference, 8<sup>th</sup> - 12<sup>th</sup> Sept. 2015 at the Imperial College in London, UK. Invitation by Prof. Emma Hart and Jennifer Willies.

**2014:** Robots & honeybees: Establishing behavioural feedback loops between animals and machines. In: Symposium “Emergent social behaviours in bio-hybrid systems” at Living Machines 2014, Milano, Italy, 30th July – 1st August 2014. Invitation by Prof. Stuart Wilson.

**2014:** Evolving bio-hybrid societies of animals and robots. Opening Keynote at the EvoStar 2014 Conference at Granada, Spain 23-25 April. Invitation by Jennifer Willies and Prof. Emma Hart and Prof. J.J. Merelo.

**2014:** Evolvierende bio-hybride Gesellschaften. Akademie-Vortragsreihe “Digitale Gesellschaft: Erkennen – Manipulieren – Schützen – Produzieren“ of the Nordrhein-Westfälische Akademie der Wissenschaften und der Künste, Düsseldorf, Germany, 9th April 2014. Invitation by Prof. Franz Rammig.

**2014:** ASSISI\_bf: Advocating bio-hybrid mixed societies of robots and animals. FET Proposers' Day. 20<sup>th</sup> Jan. 2014, at DIAMANT Conference & Business Centre in Bruxelles. Invitation by Walter van der Velde, Christiane Wilzeck and Teresa De Martino.

**2013:** Schwarmintelligenz und bio-hybride Gesellschaften. Lecture at "Biologisches Kolloquium" at the University of Bonn. 2<sup>nd</sup> Dec. 2013. Invitation by Prof. Gerhard von der Emde.

**2013:** Embodied & collective intelligence in natural and artificial autonomous agents. Lecture at the "Informationskolloquium" of the Department of Computer Science, University of Paderborn. 12<sup>th</sup> Nov. 2013. Invitation by Junior-Prof. Dr. Heiko Hamann.

**2013:** The new Cyborgs: Robots and Animals Forming a Mixed Society? Lecture at the IEEE Croatian Section 2013 Lecture Series organized by Control Systems Chapter (CS23) and Robotics and Automation Chapter (RA24). 5<sup>th</sup> Nov. 2013 at University of Zagreb, LARICS, Invitation by Dr. Stjepan Bogdan.

**2013:** "Was Roboter von Tieren und BiologInnen von Robotern lernen können". Vita Activa Vortragsreihe, University of Graz. 19<sup>th</sup> March 2013.

**2013:** "From biology & robots to bio-hybrid systems: establishing adaptive social cyborgs". Invited talk in the workshop "Emergent social behaviours in bio-hybrid systems" at Living Machines 2013, London, UK, 29th July - 2rd August 2013.

**2013:** "Collective artificial intelligence in autonomous embodied agents". University of Manchester (U.K.) 19<sup>th</sup> June 2013. Invitattion Dr. Alexandru Stancu.

**2012:** "Insects – Robots – Humans – Philosophy of the collective cognition: A journey through the mind of the masses". 6th of September 2012. ETSU, USA.

**2012:** "What is the IQ of one ant or one simple robot? And what if there are more than one to take the test?" 10th of October 2012. ETSU, USA.

**2012:** "Terminator, Matrix and Star Wars: How (far) will robots develop in our lifetime?" 1st of November 2012. ETSU, USA.

**2012:** Invited lecture in the Department Seminar of the Department for Biology. 3<sup>rd</sup> of October 2012, ETSU, USA. Invitation by Dr. I. Karsai.

**2012:** Invited talk at the Seminar for the Institute for Quantitative Biology (IQB). 24th of October 2012. ETSU, USA. Invitation by Dr. Debra Knisley.

**2012:** Invited talk in at the class "Great Ideas in Science". 29th of November 2012. ETSU, USA. Invitation by Dr. D.W. Harker and Dr. F.B. Hagelberg.

**2012:** Invited talk in the class "Modern drama" on swarm robots in theatre plays. 19h of November 2012. ETSU, USA. Invitation by Dr. K. Weiss.

**2012:** Round table on collective cognition and swarm intelligence", 16th of November 2012, ETSU, USA. Invitation by Dr. Debra Knisley.

**2012:** Invited talk "From biological models to bio-inspired robots" at the University of Zagreb. 5<sup>th</sup> of April 2012, invitation by Prof. Stjepan Bogdan.

**2012:** "Collective Cognitive Robots" at the CogSys Conference 2012 (5th International Conference on Cognitive Systems), 23<sup>rd</sup> Feb. 2012, Vienna.

**2011:** Invited talk in the seminar of the Plant and Invertebrate Ecology Department at Rothamsted Research, Harpenden, UK on the 2nd November 2011. Title "Honeybees, robots and other living things" (invitation by Dr. Matthias Becher and Dr. Juliet Osborne).

**2011:** "Honeybees & robots: Collective decision making and coordination in autonomous swarm systems" in the "Artificial Intelligence Seminar" at the Information Sciences Institute, University of Southern California (invitation bei Wei-Min Shen)

**2011:** Demonstration (in presentation form) "Spatial computing in modular robotics" at the workshop "Spatial Computing" (10min) 3rd Oct. 2011, SASO 2011, Ann Arbor, MI, USA.

**2011:** "Simemould - a collective and distributed intelligence" in the course "Holistische Wissenschaften" ("holistic sciences"), LVA-No: 7771090, at the Universität für Bodenkultur (BOKU) Vienna, Austria (invited by Prof. Thomas Prohaska)

**2010:** Workshop: 2010 IEEE International Conference on Robotics and Automation, Anchorage, Alaska, May 3-8, 2010, Workshop on Bio-Inspired Self-Organizing Robotic Systems. Title: Bio-Inspiration and Artificial Evolution in Collective Robotics.

**2010:** Workshop of the Research Core Area "Modelling and Simulation". Titel: Self-organized biological systems: Modelling, Simulation and Artificial Evolution.

**2009:** EU FET proactive external consultation workshop "fundamentals of collective adaptive systems". Title: "Creating adaptive systems that are as rich as their natural counterparts? Challenges for Evolvability". 3.-4. November 2009, Leuven, Belgium.

**2009:** Workshop/info-day "ICT on tour: Cognitive systems, Interaction, Robotics" of the FFG (Forschungsförderungsgesellschaft) Title: "Erfahrungsbericht aus dem RP7 "Replicator" oder die Biologie als Vorlage für robotische Kontrollarchitekturen". TU Graz, 10.12.2009.

**2008:** Workshop "Cognitive Robotics" (26.6.08 Budapest), invited talk by George Kampis, Collegium Budapest. Title: "Why robots are suitable models for the research of swarm phenomena"

**2008:** Workshop on Modelling Complex Biological Systems, 17th-18<sup>th</sup> April 2008, Uppsala, Sweden. Organized by: David Sumpter. "Individual-based models of honeybee intra-colonial regulation: Task-selection, nutrient allocation, brood care and navigation".

**2007:** "Complex Behavior: From honeybees to robot swarms". Seminar of the Departments of Biological Sciences & Health Sciences, ETSU, Jonson City, TN, USA. (Seminar BIOL-5700, invited by the organizer Zulfiqar Ahmad)

**2005:** "Swarm Intelligence and Self-Organization in Biology". Course Number 621.150, Seminar on Optimization and Control in Physiological Systems (for Mathematicians and Life Scientists) (2 hours of course credit) organized by: F. Kappel, T. Kenner, D. Schneditz, J. Batzel, D. Auerbach, M. Bachar, M. Fink. (Spezialforschungsbereich F-003) sponsored by the Austrian Science Fund, Graz, Austria.

**2005:** "Multi-Agentensimulation der dezentralen Regulation der Arbeitsteilung bei Honigbienen", at the „2nd Day of science”, organized by CEQUACOS, Center for Quantitative and Computational Sciences, Graz, Austria.

**2002:** "Multiagenten Simulation in der Biologie", at the “1<sup>st</sup> Day of Science”, organized by CEQUACOS, Center for Quantitative and Computational Sciences, Graz, Austria.

### ***Public Exhibitions:***

**2024:** Exhibition “HIVEOPOLIS: A Biohybrid Beehive” of the Hiveropolis fungus hive and of the digital brood comb in the Communication Parcour exhibit (one-year exhibition) in the European Commission’s Piazza Project, Brussels (in the Foyer of the Berlaymont, Brussels)

**2024:** Exhibiting Hiveopolis technology at the EIC Summit 2024, 18<sup>th</sup>-20<sup>th</sup> March 2024 in Brussels

**2024:** Exhibiting Hiveopolis technology at the Research & Innovation Days 2024, 20<sup>st</sup>-21<sup>nd</sup> March 2024 in Brussels

**2023:** Exhibition of Hiveopolis & RoboRoyale technology at the “BioBienenApfel” event in Vienna, Austria, 30<sup>th</sup> of March.

**2023:** Exhibition “Beeing/Beecoming: Scutoid Habitats”, Club Hybrid, AKT Pavilion. 3D printed clay modules holding mycelium composites as an insect-friendly algorithmic design demonstration. Technologies from EU project Hiveopolis, made in the Artificial Life Lab Graz.

**2022:** Exhibition of Hiveopolis and RoboRoyale prototypes at the “Lange Nacht der Forschung” at the Aula of the University of Graz, 20<sup>th</sup> of May.

**2022:** Semi-public exhibition of several Hiveopolis prototypes to Othmar Karas (Vice-President European Parliament) and Katrin Hohensinner (Managing Director of Frutura, Austria) with the President of the University of Graz, Dr. Peter Riedler at the University of Graz (Aula and Labs), 14<sup>th</sup> of May.

**2022:** Exhibition of several Hiveopolis prototypes prototype together with Sebastian Vettel in Spielberg, Austria, as a side event of the F1-GrandPrix. 11<sup>th</sup> July.

**2022:** Exhibition of several Hiveopolis prototypes and one RoboRoyale prototype to public media (co-hosted with Sebastian Vettel and Lisa-Marie Schiffner) at the “BioBienenApfel” Kickoff event in Munich, 27<sup>th</sup> of April.

**2022:** Exhibition “I.N.S.E.C.T. Wall Twin: Designing for and with Insects, Fungi, and Humans.” In Newcastle upon Tyne, UK. 3D printed clay modules (developed in the EU project Hiveopolis in the Artificial Life Lab Graz) holding mycelium composites as an insect-friendly facade tiling installation.

**2022:** Exhibition of various prototypes and experimental research setups in 2 distinct shows to participants of the hackathon “Change” and the “Brain, Behavior & Society” Springschool at the University of Graz, 8<sup>th</sup> of April.

**2021:** Exhibition at the “STEIERMARK SCHAU: was sein wird“ at the Kunsthau Graz, Austria (April - October 2021) with the title "HIVEOPOLIS: Beehives of the Future", exhibiting the ongoing technological developments to communicate with honeybees.

**2021:** Exhibition at the „STEIERMARK SCHAU: was sein wird“ at the Kunsthau Graz, Austria (April - October 2021) with the title "The Living Arch: A Study Model for a Novel

"Wellbeing Architecture for Honeybees", exhibiting the sustainable and organic construction method of HIVEOPOLIS hives.

**2019:** Exhibition at the VIENNA DESIGN WEEK "HIVEOPOLIS: Biohybrid superorganisms diversify urban ecological niches", exhibiting the work of the EU Project HIVEOPOLIS towards the smart beehive of the future.

**2019:** Exhibition at the Digital Design Market Platform – RESPOND FESTIVAL, Copenhagen, Denmark: "Intelligent Beehives of the Future", showcasing the HIVEOPOLIS smart beehive of the future. Invitation by: COPENHAGEN MAKER

**2019:** Exhibition at the VIENNA MAKER FAIRE 2019: "(make)ROOM FOR SHROOM".

**2018:** Ars Electronica Festival, Linz, Österreich (06.09.2018 – 10.09.2018)

**2018:** Exhibition on shaping Europe's digital future at ICT 2018, Vienna: FET-Proactive subCULTron project at Exhibition booth C03 (04.12.2018 - 06.12.2018).

**2017:** Bienentage, Graz, Österreich (22.04.2017 – 23.04.2017)

**2017:** Press event on subCULTron at Arsenale, Venice, Italy (14.09.2017- 15.09.2017).

**2016:** Ars Electronica Festival, Linz, Österreich (08.09.2016-12.09.2016)

**2016:** Grazer Frühjahrsmesse "Grazer Frühjahrsmesse macht Schule: "Wunderwelt Bienen", Graz, Österreich (28.04-2016 - 02.05.2016)

**2015:** EXPO 2015 "subCulTron underwater robot installation", Venice, Italy (16.10.2015 – 31.10.2015)

**2014:** CeBit 2014, "CoCoRo underwater robot installation", Hannover, Germany (10.03.2014 – 14.03.2015)

**2014:** Multiple live presentations of honeybee-inspired swarm robots. TEDxGRAZ talks, Graz, Old University, 12th Nov. 2014. Invitation by Friso Schopper.

**2013:** Live presentation of a robot swarm performing the honeybee-inspired robots at "Tag der Naturwissenschaften" at the Aula of the Karl-Franzens-University Graz (16.11.2013).

**2010:** Exhibition of our bio-robotic swarms at the "RESEARCH 2010" in Graz, Austria (11.6.-12.6.2010).

**2010:** Museum installation of a robotic implementation of a phosphorescent ant-trail system in the museum "Haus der Wissenschaften" at the exhibition named "Abenteuer Wissenschaft 3", 24 performances.

**2010:** Theater performance of swarm robotic algorithms supervised/consulted by the AL-Lab Graz in the theatre play "2012 – Übermorgen ist zweifelhaft" at the "Münchner Kammerspiele" by video-, performance- and theater-artist Chris Kondek (<http://www.youtube.com/watch?v=FERe9LfFZl4>), 6 performances.

**2006:** Museum installation of a robot swarm (20 JASMINE robots) in the museum “Haus der Wissenschaften” at the exhibition named “Nobelpreisträger”, which was partially focused on the work and life of Nobel price winner Karl von Frisch.

### ***Additional Management, Media-related & Teaching Qualifications:***

**2019:** Training at UNIGRAZ: “Communicating feedback” (1 day)

**2019:** Training at TU Graz: “Protect and exploit your scientific results – an overview of IPR protection and exploitation possibilities” (1 day)

**2017:** UNISTART - Basic training modules 1 & 2: “Introduction to leadership & human ressource development as a leadership objective” (0.5 days)

**2017:** UNISTART - Basic training module 3: “Employment law and staff management as a leadership skill” (1 day)

**2017:** UNISTART - Basic training module 4: “Leading teams and groups” (2 days)

**2017:** UNISTART - Basic training module 5: “Hard facts of leadership” (1 day)

**2017:** UNISTART - Basic training module 5: “Research – Teach – Lead: Challenges for scientific leaders” (1 day)

**2017:** UNISTART – Advanced module W5: “Conflict management” (2 days)

**2017:** UNISTART – Advanced module W6: “Negotiation management” (1 day)

**2017:** UniIT Training: “Constructing and conducting online tests with Perception” (1 day)

**2002 - 2003:** Teacher training in “eLearning” and “web-based teaching” at the University of Applied Sciences Joanneum, Graz (3 month course).

**2002:** Teacher training in “eLearning” and “web-based teaching” at the University of Graz (3-month course).

**1997:** Teacher training "Teaching and learning in on-the-job-trainings" (WIFI, 80 hours course).

**1989-2003:** Part-time professional photographer at the company “Foto Schmickl”, Graz.

# Publications

## **Theses:**

Habilitation thesis: **Schmickl T. (2012)** “*The Collective Physiology of the Swarm: Modelling Self-Organization, Self-Regulation and Swarm-Intelligence of Distributed Systems in Biology and Bio-Robotics*”, Karl-Franzens University Graz.

Ph.D. thesis: **Schmickl T. (2001)** "Regulation of brood development in the honeybee (*Apis mellifera* L.): Feedback mechanisms and survival strategies of a superorganism", Karl-Franzens University of Graz.

Master thesis: **Schmickl T. (1998)** “Die Erfassung des mikrobiologischen Status in der Innenraumluft von Krankenanstalten“, University of Salzburg. ("Assessment of the microbiological status of the indoor air in styrian public hospitals").

## ***Editing of special issues in scientific journals:***

1. Romano, D., **Schmickl, T.**, Hamann, H., Farshad, A., Wahby, M., (2023) “Biohybrids, Bioinspired and Biomimetic Agents for Dynamic and Complex Environments” in *Sensors*, MDPI.
2. **Schmickl, T.**, Romano, D., Zahadat, P., Porfiri, M. (2023) “Biohybrid Systems: Bioinspired and Biomimetic Robots Interacting with Living Organisms” in *Bioinspiration & Biomimetics*, IOPscience.
3. Hamann, H., **Schmickl, T. (2011)** Special Issue: “Modelling the Swarm – Analysing biological and engineered swarm systems” in *Mathematical and Computer Modelling of Dynamical Systems*, Taylor & Francis. DOI: 10.1080/13873954.2011.601426.

## **Books:**

- Karsai, I., **Schmickl, T.**, Kampis, G. (2020). Resilience and Stability of Ecological and Social Systems. Springer Cham., ISBN 978-3-030-54560-4

## ***Peer-reviewed full articles in journals, book series and proceedings:***

1. **Schmickl, T. (2024).** Memetic robots. *Nature Machine Intelligence*, 1-2, <https://doi.org/10.1038/s42256-024-00959-8>
2. **Schmickl, T. & Romano, D. (2024).** Robots and animals teaming up in the wild to tackle ecosystem challenges. *Science Robotics*, 9(96), eado5566.
3. Ulrich, J., Stefanec, M., Rekabi-Bana, F., Fedotoff, L.A., Rouček, T., Gündeğer, B.Y., Saadat, M., Blaha, J., Janota, J., Hofstadler, D.N. and Žampachů, K., Keyvan, E.E.,

- Erdem, B., Şahin, E., Alemdar, H., Turgut, A.E., Arvin, F., **Schmickl, T.**, Krajník, T. (2024) Autonomous tracking of honey bee behaviors over long-term periods with cooperating robots. *Science Robotics* 9, no. 95: eadn6848.
4. Gogoi, N., Helmer, N., Wu, C., Thenius, R., Casson, A., **Schmickl, T.** & Arvin, F. (2024). Biohybrid Sensors for Underwater Monitoring. In *IEEE Applied Sensing Conference*. IEEE.
  5. Blaha, J., Mikula, J., Vintr, T., Janota, J., Ulrich, J., Rouček, T., Rekabi-Bana, F., Fedotoff, L.A., Stefanec, M., **Schmickl, T.**, Arvin, F., Kulich, M. & Krajník, T. (2024). Effective Searching for the Honeybee Queen in a Living Colony. In: *2024 IEEE 20th International Conference on Automation Science and Engineering (CASE)* (pp. 3675-3682). IEEE.
  6. Rekabi-Bana, F., Saadat, S., Kalantaryardebily, N., Stefanec, M., Fedotoff, L.A., Pan, H., Krajník, T., **Schmickl, T.**, Arvin, F. (2024) Active Vibration Reduction for the Autonomous Observation Mechanism. In: *2024 IEEE Conference on Control Technology and Applications (CCTA)*, pp. 805-810. IEEE, 2024.
  7. Stefanec, M., Fedotoff, L., Arvin, F., **Schmickl, T.**, Krajník, T. (2024) Towards Robotic Mapping of a Honeybee Comb. In: *2024 International Conference on Manipulation, Automation and Robotics at Small Scales (MARSS)*, pp. 1-6. IEEE, 2024.
  8. Ilgün, A., Szopek, M., **Schmickl, T.** (2024) The Eusocial Cathedral and the Buzzara: A Novel Synthesis from De-and Reconstructing the Living and the Artificial. *The Cultures of Entanglement: On Nonhuman Life Forms in Contemporary Art* 233 (2024): 327.
  9. Romano, D., Porfiri, M., Zahadat, P., **Schmickl, T.** (2024) Animal–robot interaction—an emerging field at the intersection of biology and robotics. *Bioinspiration & Biomimetics* 19, no. 2 (2024): 020201.
  10. Barmak, R., Hofstadler, D. N., Stefanec, M., Piotet, L., Cherfan, R., **Schmickl, T.**, Mondada, F., Mills, R. (2024). Biohybrid superorganisms — on the design of a robotic system for thermal interactions with honeybee colonies. *IEEE Access* 12, 50849-50871. DOI: 10.1109/ACCESS.2024.3385658
  11. Rajewicz, W., Wu, C., Romano, D., Campo, A., Arvin, F., Casson, A.J., van Vuuren G.J., Stefanini, C., Varughese, J.C., Lennox, B., Schönwetter-Fuchs, S., **Schmickl, T.**, Thenius, R. (2023). Organisms as sensors in biohybrid entities as a novel tool for in-field aquatic monitoring. *Bioinspiration & Biomimetics*, 19(1), 015001.
  12. Rajewicz, W., Romano, D., **Schmickl, T.**, Thenius, R. (2023). Daphnia's phototaxis as an indicator in ecotoxicological studies: A review. *Aquatic Toxicology*, 106762, DOI: 10.1016/j.aquatox.2023.106762
  13. **Schmickl, T.**, Karsai, I. (2023). Self-complexification through integral feedback in eusocial paper wasps of various levels of sociality. *Heliyon* 9(9), e20064. DOI: 10.1016/j.heliyon.2023.e20064.
  14. Hamann, H., **Schmickl, T.** (2023). Free Lunch in Evolutionary Embodied Computation in Modular Robotics. In: *Proceedings of the ALIFE 2023: Ghost in the Machine: Proceedings of the 2023 Artificial Life Conference*. MIT Press, Article: isal\_a\_00569, 128. DOI: [https://doi.org/10.1162/isal\\_a\\_00569](https://doi.org/10.1162/isal_a_00569).

15. Rajewicz, W., **Schmickl, T.**, Thenius, R. (2023). Daphnia as a living sensor for underwater biohybrid systems. In: *Proceedings of the ALIFE 2023: Ghost in the Machine: Proceedings of the 2023 Artificial Life Conference*. MIT Press, Article isal\_a\_00572, 6. DOI: [https://doi.org/10.1162/isal\\_a\\_00572](https://doi.org/10.1162/isal_a_00572).
16. Rajewicz, W., Helmer, N., **Schmickl, T.**, Thenius, R. (2023). Living Organisms as Sensors for Biohybrid Monitoring Systems. In: *Proceedings of the Conference on Biomimetic and Biohybrid Systems* (pp. 348-362). Cham: Springer Nature Switzerland.
17. Lazic, D., **Schmickl, T.** (2023). Will biomimetic robots be able to change a hivemind to guide honeybees' ecosystem services? *Bioinspiration & Biomimetics*, 18(3), Article 035004.
18. Barmak, R., Stefanec, M., Hofstadler, D. N., Piotet, L., Schönwetter-Fuchs-Schistek, S., Mondada, F., **Schmickl, T.**, Mills, R. (2023). A robotic honeycomb for interaction with a honeybee colony. *Science Robotics*, 8(76), eadd7385.
19. Rekabi-Bana, F., Stefanec, M., Ulrich, J., Keyvan, E. E., Rouček, T., Broughton, G., Gündeğer, B.Y., Sahin, Ö., Turgut, A.E., Sahin, E., Krajinik, T., **Schmickl, T.**, Arvin, F. (2023). Mechatronic Design for Multi Robots-Insect Swarms Interactions. In: *Proceedings of the 2023 IEEE International Conference on Mechatronics (ICM)* (pp. 1-6). IEEE.
20. Vogrin, M., Rajewicz, W., **Schmickl, T.**, Thenius, R. (2023). Improving the Accuracy of a Biohybrid for Environmental Monitoring. *Sensors*, 23(5), 2722.
21. Vogrin, M., Wood, G., **Schmickl, T.** (2023). Confirmation Bias as a Mechanism to Focus Attention Enhances Signal Detection. *Journal of Artificial Societies and Social Simulation*, 26(1), 2. doi: 10.18564/jasss.4954
22. Žampachů, K., Ulrich, J., Rouček, T., Stefanec, M., Dvořáček, D., Fedotoff, L., Hofstadler, D.N., Rekabi-Bana, F., Broughton, G., Arvin, F., **Schmickl, T.**, Krajinik, T. (2022). A vision-based system for social insect tracking. In: *Proceedings of the 2<sup>nd</sup> International Conference on Robotics, Automation and Artificial Intelligence (RAAI)* (pp. 277-283). IEEE.
23. **Schmickl, T.** (2022) Strong Emergence Arising from Weak Emergence. In: *Complexity*, Article 9956885. DOI: 10.1155/2022/9956885
24. Ilgün, A., **Schmickl, T.** (2022) Mycelial Beehives of HIVEOPOLIS: Designing and Building Therapeutic Inner Nest Environments for Honeybees. *Biomimetics* 7(2) (ISSN 2313-7673), MDPI, Basel CH. DOI: 10.3390/biomimetics7020075
25. Rajewicz, W., Romano, D., **Schmickl, T.**, Thenius, R. (2022) Lifeforms potentially useful for automated underwater monitoring systems. In: *Proceedings of ALIFE 2022: The 2022 Conference on Artificial Life*. MIT Press. DOI 10.1162/isal\_a\_00527
26. Vogrin, M., Wood, G., **Schmickl, T.** (2022) Modelling a Common Cognitive Bias and a Simple Heuristic to Overcome it. In: *Proceedings of ALIFE 2022: The 2022 Conference on Artificial Life*. MIT Press. DOI 10.1162/isal\_a\_00508

27. Stefanec, M., **Schmickl, T.** (2022) PPS<sup>3D</sup>: A 3D Variant of the Primordial Particle System. In: Proceedings of *ALIFE 2022: The 2022 Conference on Artificial Life*. MIT Press. DOI 10.1162/isal\_a\_00510
28. Stefanec, M., Hofstadler, D. N., Krajník, T., Turgut, A. E., Alemdar, H., Lennox, B., Şahin, E., Arvin, F., **Schmickl, T.** (2022) A Minimally Invasive Approach Towards “Ecosystem Hacking” With Honeybees. *Frontiers in Robotics and AI*, 9, Article 791921. DOI 10.3389/frobt.2022.791921
29. Ilgün, A., Mills, R., Mondada, F., **Schmickl, T.** (2022). A study model for reconstructing urban ecological niches. In: *Structures and Architecture. A Viable Urban Perspective?* (pp. 75-82). CRC Press.
30. Rajewicz, W., **Schmickl, T.**, Thenius, R. (2022). The Use of Robots in Aquatic Biomonitoring with Special Focus on Biohybrid Entities. In: Müller, A., Brandstötter, M. (eds) *Advances in Service and Industrial Robotics*. RAAD 2022. Mechanisms and Machine Science, vol 120. Springer, Cham. [https://doi.org/10.1007/978-3-031-04870-8\\_72](https://doi.org/10.1007/978-3-031-04870-8_72)
31. Szopek, M., Stokanic, V., Radspieler, G., **Schmickl, T.** (2021). Simple physical interactions yield social self-organization in honeybees. *Frontiers in Physics*, 9, 576.
32. Stefanec, M., Oberreiter, H., Becher, M. A., Haase, G., **Schmickl, T.** (2021). Effects of sinusoidal vibrations on the motion response of honeybees. *Frontiers in Physics*, 9, 318.
33. Rajewicz, W., Romano, D., Varughese, J. C., Vuuren, G. J. V., Campo, A., Thenius, R., **Schmickl, T.** (2021). Freshwater organisms potentially useful as biosensors and power-generation mediators in biohybrid robotics. *Biological Cybernetics*, 115(6), 615-628.
34. Lazic D., **Schmickl, T.** (2021) Can Robots Inform a Honeybee Colony’s Foraging Decision-Making? In: Proceedings of *ALIFE 2021: The 2021 Conference on Artificial Life*. MIT Press.
35. Ilgün, A., Angelov, K., Stefanec, M., Schönwetter-Fuchs, S., Stokanic, V., Vollmann, J., Hofstadler, D.N., Kärcher, M., Mellmann, H., Taliaronak, V., Kviesis, A., Komasilovs, V., Becher, M.A., Szopek, M., Dormagen, D.M., Barmak, R., Bairaktarov, E., Broisin, M., Thenius, R., Mills, R., Nicolis, S.C., Campo, A., Zacepins, A., Petrov, S., Deneubourg, J.-L., Mondada, F., Landgraf, T., Hafner, V.V., **Schmickl T.** (2021) Bio-Hybrid Systems for Ecosystem Level Effects. In: Proceedings of *ALIFE 2021: The 2021 Conference on Artificial Life*. MIT Press.
36. Thenius, R., Rajewicz, W. Varughese, J.C., Schoenwetter-Fuchs, S., Arvin, F., Casson, A., Wu, C., Lennox, B., Campo, A., van Vuuren, G.J., Stefanini, C., Romano D., **Schmickl, T.** (2021) Biohybrid Entities for Environmental Monitoring. In: Proceedings of *ALIFE 2021: The 2021 Conference on Artificial Life*. MIT Press.
37. **Schmickl, T.**, Stefanec, M., Hofstadler, D.N., Krajnik, T., Turgut, A.E., Arvin, F. (2021). The queen and her robotic court: a minimally-invasive form of ecosystem hacking. In: Proceedings of the EUROSIS 5th Annual Science Fiction Prototyping Conference 2021, eds. Philippe Geril, pp. 5-12.
38. **Schmickl, T.**, Szopek, M., Mondada, F., Mills, R., Stefanec, M., Hofstadler, D., Lazic, D., Barmak, R., Bonnet, F., Zahadat, P. (2021) Social integrating robots suggest

- mitigation strategies for ecosystem decay. *Frontiers in Bioengineering and Biotechnology, Bionics and Biomimetics* 9, 100762.
39. **Schmickl T.**, Zahadat P., Hamann H. (2021) Wankelmut: A Simple Benchmark for the Evolvability of Behavioral Complexity. *Applied Sciences* 11(5), 1994. <https://doi.org/10.3390/app11051994>.
40. Schranz, M., Di Caro, G. A., **Schmickl, T.**, Elmenreich, W., Arvin, F., Şekercioğlu, A., & Sende, M. (2021). Swarm Intelligence and cyber-physical systems: Concepts, challenges and future trends. *Swarm and Evolutionary Computation*, 60, 100762.
41. Hornischer, H., Varughese, J. C., Thenius, R., Wotawa, F., Füllsack, M., & **Schmickl, T.** (2021). CIMAX: collective information maximization in robotic swarms using local communication. *Adaptive Behavior*, 1059712320912021.
42. Wang, S., Turgut, A.E., **Schmickl, T.**, Lennox, B., Arvin, F. (2020) Investigation of Cue-based Aggregation Behaviourin Complex Environments". In: Investigation of Cue-Based Aggregation Behaviour in Complex Environments - Lecture Notes of the Institute for Computer Sciences, Social Informatics and Telecommunications Engineering book series (LNICST) 350, 18-36.
43. Vogrin, M., Stefanec, M., **Schmickl, T.** (2020) Social Distancing in Robot Swarms: Modulating Exploitation and Exploration Without Signal Exchange. Proceedings of the 2020 IEEE SSCI (Symposium Series on Computational Intelligence) conference, 2233-2240.
44. Luneckas, T., Luneckas, M., Salem, Z., Szopek, M., **Schmickl, T.** (2020) Convolutional Neural Network for Honeybee Density Estimation. Proceedings of the 2020 IEEE SSCI (Symposium Series on Computational Intelligence) conference, 2558-2566.
45. Vogrin, M., Wood, G., **Schmickl, T.** (2020) Electric Love: Analyzing Human Mate Selection Dynamics in a Digital Environment. Proceedings of the 8<sup>th</sup> Conference on Computation, Communication, Aesthetics & X (xCoAx) 2020 conference pp. 148-159
46. Varughese, J. C., Hornischer, H., Zahadat, P., Thenius, R., Wotawa, F., **Schmickl, T.** (2020) A swarm design paradigm unifying swarm behaviors using minimalistic communication. *Bioinspiration & Biomimetics*, 15(3), 036005.
47. Wahby, M., Heinrich, M.K., Hofstadler, D.N., Petzold, J., Kuksin, I., Zahadat, P., **Schmickl, T.**, Ayres, P., Hamann, H. (2019) Robotic Sensing and Stimuli Provision for Guided Plant Growth. <https://www.jove.com/video/59835/robotic-sensing-and-stimuli-provision-for-guided-plant-growth> DOI: doi:10.3791/59835
48. Bonnet F., Mills R., Schönwetter-Fuschs S., Szopek M., Halloy J., Bogdan S. Correia L., Mondada F., **Schmickl, T.** (2019) Robots mediating interactions between animals for interspecies collective behaviors. *Science Robotics* 4(28), eaau7897, DOI: 10.1126/scirobotics.aau7897
49. Heinrich M.K., von Mammen S., Hofstadler D.N., Wahby M., Zahadat P., Skrzypczak T., Soorati M.D., Krela R., Kwiatkowski W., **Schmickl T.**, Ayres P., Stoy K., Hamann H. (2019) Constructing Living Buildings: A Review of Relevant Technologies for a Novel Application of Biohybrid Robotics. *Journal of the Royal Society Interface* 16, DOI 10.1098/rsif.2019.0238

50. Varughese, J., Hornischer, H., Thenius, R., Wotawa, F., **Schmickl, T. (2019)**. Collective Event Detection Using Bio-inspired Minimalistic Communication in a Swarm of Underwater Robots. In: Fellermann, H., Bacardit, J., Goñi-Moreno, A., Füchslin, R.M. (eds.) Proceedings of the 2019 ALIFE Conference, Newcastle, UK, pp. 634-641.
51. Wang, W.-C., **Schmickl, T. (2019)** Collective Motion as an Ultimate Effect in Crowded Selfish Herds. *Scientific Reports* 9:6618. DOI: 10.1038/s41598-019-43179-6
52. Wahby, M., Petzold, J., Eschke, C., **Schmickl, T.**, Hamann, H. **(2019)** Collective Change Detection: Adaptivity to Dynamic Swarm Densities and Light Conditions in Robot Swarms. In: Fellermann, H., Bacardit, J., Goñi-Moreno, A., Füchslin, R.M. (eds.) Proceedings of the 2019 ALIFE Conference, Newcastle, UK, pp. 642-649
53. Varughese, J., Moser, D., Thenius, R., Wotawa, F., **Schmickl, T. (2019)** swarmFSTaxis: Borrowing a Swarm Communication Mechanism from Fireflies and Slime Mold. In: Ted Carmichael & Andy Collins (eds.) Complex Adaptive Systems: Views from the Physical, Natural, and Social Sciences. Norfolk, Virginia, USA. Springer, pp 213-222.
54. Kengyel D., Zahadat P., Wotawa F., **Schmickl T. (2019)** Towards swarm level optimisation: the role of different movement patterns in swarm systems. *International Journal of Parallel, Emergent and Distributed Systems* 34(3), pp 241-259.
55. Kimura, T., Ohashi, M., Crailsheim, K., **Schmickl, T.**, Okada, R., Radspieler, G., Isokawa, T., Ikeno, H., **(2019)** A Heuristic Trajectory Decision Method to Enhance the Tracking Performance of Multiple Honeybees on a Flat Laboratory, In: *J-STAGE*, 113 Volume 32, pp 113-122, doi.org/10.5687/iscie.32
56. **Schmickl T.**, Karsai I. **(2018)** Integral feedback control is at the core of task allocation and resilience of insect societies. *Proceedings of the National Academy of Science (PNAS)* 201807684, DOI: 10.1073/pnas.1807684115
57. Wahby M., Heinrich M. K., Hofstadler D. N., Neufeld E., Kuksin I., Zahadat P., **Schmickl T.**, Ayres P., Hamann H. **(2018)** Autonomously shaping natural climbing plants: a bio-hybrid approach. *Royal Society Open Science* 5(10), 180296.
58. Wahby M., Heinrich M. K., Hofstadler D. N., Zahadat P., Risi S., Ayres P., **Schmickl T.**, Hamann H. **(2018)** A robot to shape your natural plant: the machine learning approach to model and control bio-hybrid systems. *Proceedings of the Genetic and Evolutionary Computation Conference 2018 (GECCO'18)*, pp 165-172.
59. Varughese, J.C., Hornischer, H., Thenius, R., Zahadat, P., Wotawa, F., **Schmickl, T. (2018)** Introduction to WOSPP: wave oriented swarm programming paradigm. *CoRR* abs/1804.04202.
60. Zahadat P., **Schmickl T. (2018)** Locomotion as a Result of Displacement of Resources, Proceedings of the Artificial Life Conference 2018 (ALIFE'18), pp 232-233.
61. Mariano P., Salem Z., Mills R., Schönwetter-Fuchs-Schistek S., Correia L., **Schmickl T. (2018)** Evolving robot controllers for a bio-hybrid system. Proceedings of the Artificial Life Conference 2018 (ALIFE'18), pp 155-162.
62. Salem Z., Radspieler G., Gripasic G., **Schmickl T. (2018)** Estimating Dynamics of Honeybee Population Densities with Machine Learning Algorithms. *Machine Learning*,

- Optimization, and Big Data. MOD 2017. LNCS. vol. 10710. Springer, Cham. 10710 (2018), 309-321
63. Zahadat P., Hofstadler, D., **Schmickl T. (2018)** Morphogenesis as a Collective Decision of Agents Competing for Limited Resource: a Plants Approach. In: Dorigo M., Birattari M., Blum C., Christensen A., Reina A., Trianni V. (eds) Swarm Intelligence. ANTS 2018. *Lecture Notes in Computer Science*, vol 11172, pp 84-96. Springer, doi: [https://doi.org/10.1007/978-3-030-00533-7\\_7](https://doi.org/10.1007/978-3-030-00533-7_7).
  64. Varughese, J. C., Thenius, R., Leitgeb, P., Wotawa, F., **Schmickl, T. (2018)** A Model for Bio-Inspired Underwater Swarm Robotic Exploration. In: Felix Breitenecker, Wolfgang Kemmetmüller, Andreas Körner, Andreas Kugi, Inge Troch (eds.) 9th Vienna International Conference on Mathematical Modelling. *IFAC-PapersOnLine*, 51(2), 385-390, DOI: <https://doi.org/10.1016/j.ifacol.2018.03.066>
  65. Thenius, R., Varughese, J. C., Moser, D., **Schmickl, T. (2018)** WOSPP-A Wave Oriented Swarm Programming Paradigm. In: Felix Breitenecker, Wolfgang Kemmetmüller, Andreas Körner, Andreas Kugi, Inge Troch (eds.) 9th Vienna International Conference on Mathematical Modelling. *IFAC-PapersOnLine*, 51(2), 385-390, DOI: <https://doi.org/10.1016/j.ifacol.2018.03.065>
  66. Thenius, R., Moser, D., Varughese, J.V., Kernbach, S., Kuksin, I., Kernbach, O., Kuksina, E., Miskovic, N., Bogdan, S., Petrovic, T., Babic, A., Boyer, F., Lebastard, F., Bazeille, S., Ferrari, G.W., Donati, E., Pelliccia, R., Romano, D., van Vuuren, G.J., Stefanini, C., Morgantin, M., Campo, A., Schmickl, T. (2018) subCULTron-Cultural Development as a Tool in Underwater Robotics. In: Lewis P., Headleand C., Battle S., Ritsos P. (eds) Artificial Life and Intelligent Agents. *ALIA 2016*. Communications in Computer and Information Science, vol 732. Springer, DOI: [https://doi.org/10.1007/978-3-319-90418-4\\_3](https://doi.org/10.1007/978-3-319-90418-4_3)
  67. Zahadat, P., **Schmickl, T. (2018)** Evolving Vascular Morphogenesis Controller to Demonstrate Locomotion. In: (eds.) Proceedings of Artificial Intelligence and Signal Processing (AISP). Shiraz, Iran. IEEE. 2017. 6.
  68. **Schmickl T.**, Karsai I. (2017) Resilience of honeybee colonies via common stomach: A model of self-regulation of foraging. *PLOS ONE* 12(11): e0188004, DOI: <https://doi.org/10.1371/journal.pone.0188004>
  69. **Schmickl, T. (2017)** Fundamentalism in a social learning perspective: A memetic agent model of vegetarianism, social interaction networks and food markets. In: *2017 IEEE Symposium Series on Computational Intelligence (SSCI)*, Honolulu, HI, 2017, DOI: 10.1109/SSCI.2017.8280876
  70. Oswald, Y., **Schmickl, T. (2017)** Ultimate Ecology: How a socio-economic game can evolve into a resilient ecosystem of agents. In: *2017 IEEE Symposium Series on Computational Intelligence (SSCI)*, Honolulu, HI, 2017, DOI: 10.1109/SSCI.2017.8280876
  71. Stefanec, M., Szopek, M., Mills, R., **Schmickl, T. (2017)** Governing the swarm: Controlling a bio-hybrid society of bees & robots with computational feedback loops. In: *2017 IEEE Symposium Series on Computational Intelligence (SSCI)*, Honolulu, HI, 2017, DOI: 10.1109/SSCI.2017.8280876

72. Donati E., van Vuuren G.J., Tanaka K., Romano D., **Schmickl T.**, Stefanini C. (2017) aMussels: Diving and Anchoring in a New Bio-inspired Under-Actuated Robot Class for Long-Term Environmental Exploration and Monitoring. In: Gao Y., Fallah S., Jin Y., Lekakou C. (eds.) Towards Autonomous Robotic Systems. TAROS 2017. *Lecture Notes in Computer Science*, vol 10454. Springer, DOI: 10.1007/978-3-319-64107-2
73. Varughese, J., Thenius, R., **Schmickl, T.**, Wotawa, F. (2017) Quantification and Analysis of the Resilience of Two Swarm Intelligent Algorithms. In: Christoph Benzmüller, Christine Lisetti and Martin Theobald (eds.) GCAI 2017. 3rd Global Conference on Artificial Intelligence. Miami, Florida, USA. EPiC Series in Computing. 2017. 148 - 161. DOI:10.29007/5fhn
74. Hofstadler D. N., Wahby M., Heinrich M. K., Hamann H., Zahadat P., Ayres P., **Schmickl T.** (2017) Evolved Control of Natural Plants: Crossing the Reality Gap for User-defined Steering of Growth and Motion. In: *ACM Transactions on Adaptive and Autonomous Systems* (TAAS), 2, 3, Article 15, DOI: <https://doi.org/10.1145/3124643>
75. Zahadat P., Hofstadler D. N., **Schmickl T.** (2017) Development of Morphology Based on Resource Distribution: Finding the Shortest Path in a Maze by Vascular Morphogenesis Controller. In: 14th European Conference on Artificial Life (ECAL 2017) 4-8 September 2017, Lyon, France, DOI: 10.7551/ecal\_a\_071
76. Mariano P., Salem Z., Mills R., Zahadat P., Correia L., **Schmickl T.** (2017) Animal-guided evolutionary computation in honeybees and robots. In: Proceedings of the European Conference on Artificial Life (ECAL 2017) 4-8 September 2017, Lyon, France, DOI: 10.7551/ecal\_a\_085
77. Szopek M., Stefanec M., Bodi. Radspieler G., **Schmickl T.** (2017) A cellular model of swarm intelligence in bees and robots. In: *Proceedings of the 10th EAI International Conference on Bio-inspired Information and Communications Technologies (BICT 2017)*, DOI: <http://dx.doi.org/10.4108/eai.22-3-2017.152396>
78. Stefanec M., Szopek M., Thenius R., Radspieler G., **Schmickl T.** (2017) Robotic oligarchy: How a few members can control their whole society by doing almost nothing. In: *Proceedings of the 10th EAI International Conference on Bio-inspired Information and Communications Technologies (BICT)*, DOI: <http://dx.doi.org/10.4108/eai.22-3-2017.152412>
79. Polic M., Salem Z., Griparic K., Bogdan S., **Schmickl T.** (2017) Estimation of moving agents density in 2D space based on LSTM neural network. In: Proceedings of Evolving and Adaptive Intelligent Systems conference (EAIS 2017), DOI: 10.1109/EAIS.2017.7954842
80. Zahadat P., Hofstadler D. N., **Schmickl T.** (2017) Vascular Morphogenesis Controller: A Generative Model For Developing Morphology of Artificial Structures. In: Proceedings of the Genetic and Evolutionary Computation Conference (GECCO '17). ACM, New York, NY, USA, 163-170, DOI: <https://doi.org/10.1145/3071178.3071247>
81. Mariano P., Salem Z., Mills R., Zahadat P., Correia L., **Schmickl T.** (2017) Design choices for adapting bio-hybrid systems with evolutionary computation. In: Proceedings of the Genetic and Evolutionary Computation Conference Companion (GECCO '17). ACM, New York, NY, USA, 211-212, DOI: <https://doi.org/10.1145/3067695.3076044>

82. Salem Z., Radspieler G., Griparic K., **Schmickl T.** (2017) Estimating Dynamics of Honeybee Population Densities with Machine Learning Algorithms. In: Nicosia G., Pardalos P., Giuffrida G., Umeton R. (eds) Machine Learning, Optimization, and Big Data. MOD 2017. *Lecture Notes in Computer Science*, vol 10710. Springer, DOI: [https://doi.org/10.1007/978-3-319-72926-8\\_26](https://doi.org/10.1007/978-3-319-72926-8_26)
83. Hofstadler, D.N., Zahadat, P., **Schmickl, T.**, (2017) Vascular Morphogenesis Controller: Guiding Morphology by Competition for Resource Distribution. In: Proceedings of the Morphogenetic Engineering Workshop, at the European Conference on Artificial Life (ECAL) 2017 September 4, 2017.
84. Kimura, T., Ohashi, M., Okada, R., Crailsheim, K., **Schmickl, T.**, Radspieler, G., Isokawa, T., Ikeno H. (2017) Automatic tracking method for multiple honeybees using backward-play movies. In: Proceedings of the IEEE 2017 6th International Conference on Informatics, Electronics and Vision & 2017 7th International Symposium in Computational Medical and Health Technology (ICIEV-ISCMHT), pp. 1-4.
85. Moser D., Thenius R., **Schmickl T.** (2017) First Investigations into Artificial Emotions in Cognitive Robotics. In: Husty and Hofbaur (eds.): Medical and Service Robotics: Proceedings of the 5th International MESROB workshop, Graz, Austria, 4th - 6th July 2016. Springer, DOI: [https://doi.org/10.1007/978-3-319-59972-4\\_16](https://doi.org/10.1007/978-3-319-59972-4_16)
86. Mills R., Szopek M., Bodi M., **Schmickl T.**, Correia L. (2016) On the timescale of interactions in bio-hybrid systems. In: Eds. Carlos Gershenson, Tom Froese, Jesus M. Siqueiros, Wendy Aguilar, Eduardo J. Izquierdo and Hiroki Sayama (eds.) Late Breaking Abstracts booklet of the Artificial Life Conference 2016. 15-16.
87. Zahadat P., **Schmickl T.** (2016) Division of Labor in a Swarm of Autonomous Underwater Robots by Improved Partitioning Social Inhibition. *Adaptive Behavior* 24(2), 87-101, DOI: <https://doi.org/10.1177/1059712316633028>
88. **Schmickl T.**, Stefanec M., Crailsheim K. (2016) How a life-like system emerges from a simple particle motion law. *Scientific Reports* 6: 37969, DOI: 10.1038/srep37969
89. Karsai I., Montano E., **Schmickl T.** (2016) Bottom-up ecology: an agent-based model on the interactions between competition and predation. *Letters in Biomathematics* 2016, pp. 161-180; Vol. 3, NO 1. DOI: <http://dx.doi.org/10.1080/23737867.2016.1217756>
90. **Schmickl T.**, Karsai I. (2016) How regulation based on a common stomach leads to economic optimization of honeybee foraging. *Journal of Theoretical Biology* 389: pp. 274–286, DOI: 10.1016/j.jtbi.2015.10.036
91. Zahadat P., Hofstadler D. N., **Schmickl T.** (2016) Vascular Morphogenesis Controller: A Distributed Controller for Growing Artificial Structures. In: Sameh Elnikety, Peter R. Lewis and Christian Müller-Schloer (eds.) Proceedings of the IEEE International Workshops on Foundations and Applications of Self\* Systems. SASO 2016. 12.-16. September 2016, Augsburg, Germany. DOI:10.1109/FAS-W.2016.66.
92. Zahadat P., **Schmickl T.** (2016) Division of Labor in a Swarm of Autonomous Underwater Robots by Improved Partitioning Social Inhibition. *Adaptive Behavior* (2016), DOI: <https://doi.org/10.1177/1059712316633028>

93. Dauschan M., Thenius R., Crailsheim K., **Schmickl T. (2016)** Organising body formation of modular autonomous robots using Virtual Embryogenesis. In: Husty and Hofbaur (eds.): Medical and Service Robotics: Proceedings of the 5th International MESROB workshop, Graz, Austria, 4th - 6th July 2016. Springer, DOI: [https://doi.org/10.1007/978-3-319-59972-4\\_6](https://doi.org/10.1007/978-3-319-59972-4_6)
94. Varughese J.Ch., Thenius R., Wotawa F., **Schmickl T. (2016)** FSTT Algorithm: Can Tides Assist Bio-Inspired Gradient Taxis? In: M. Husty and M. Hofbaur (eds.): Medical and Service Robotics: Proceedings of the 5th International MESROB workshop, Graz, Austria, 4th - 6th July 2016. Springer, DOI: [https://doi.org/10.1007/978-3-319-59972-4\\_23](https://doi.org/10.1007/978-3-319-59972-4_23)
95. Varughese J. Ch., Thenius R., Wotawa F., **Schmickl T. (2016)** FSTaxis Algorithm: Bio-Inspired Emergent Gradient Taxis. In: Carlos Gershenson, Tom Froese, Jesus M. Siqueiros, Wendy Aguilar, Eduardo J. Izquierdo and Hiroki Sayama (eds.): Proceedings of the Artificial Life Conference ALIFE'16. Mexico. MIT Press. 2016. 330 – 338, DOI: [https://doi.org/10.1162/ical\\_a\\_0055](https://doi.org/10.1162/ical_a_0055)
96. Kengyel D., Zahadat P., Kunzfeld T., **Schmickl T. (2016)** Collective Decision Making in a Swarm of Robots: How Robust the BEECLUST Algorithm Performs in Various Conditions. Research Article in European Union Digital Library, DOI: <http://dx.doi.org/10.4108/eai.3-12-2015.2262332>
97. Bodi M., Szopek M., Zahadat P., **Schmickl T. (2016)** Evolving Mixed Societies: A one-dimensional modelling approach In: Proceedings of the 9<sup>th</sup> EAI International Conference on Bio-inspired Information and Communications Technologies (BICT 2015) 3.-5. December 2015, New York City, USA. ISBN 978-1-63190-100-3. Published in EAI Endorsed Transactions on Serious Games 16(3): e5, DOI: 10.4108/eai.3-12-2015.2262514. ACM. Published in the *European Union Digital Library*.
98. Hahshold, S., Polder R., Radspieler G., Szopek M., **Schmickl T.**, Crailsheim K. **(2016)** Behaviour of single young honeybees and groups of young honeybees in a temperature gradient. In: EUROIUSSI (eds.) EUROIUSSI Abstract book. 2016. 56.a
99. Zahadat P., Hahshold S., Thenius R., Crailsheim K., **Schmickl T. (2015)** From Honeybees to Robots and Back: Division of Labour based on Partitioning Social Inhibition. *Bioinspiration & Biomimetics* 10(6) (2015), DOI: 10.1088/1748-3190/10/6/066005
100. Zahadat P., **Schmickl T. (2015)** Evolving Controllers for Programmable Robots to Influence Non-Programmable Lifeforms: A Casy Study. In: *Lecture Notes in Computer Science* 9028: pp. 831-841.
101. Mills R., Zahadat P., Silva F., Mlikic D., Mariano P., **Schmickl T.**, Correia L. **(2015)** Coordination of collective behaviours in spatially separated agents. In: *Advances in Artificial Life*, ECAL 2015 (2015), pp. 579–586, MIT Press, DOI: <http://dx.doi.org/10.7551/978-0-262-33027-5-ch101>.
102. Hamann H., Whaby M., **Schmickl T.**, Zahadat P., Hofstadler D., Stoy K., Risi S., Faina A., Veenstra F., Kernbach S., Kuksin I., Kernbach O., Ayres P., Wojtaszek P. **(2015)** Flora robotica - Mixed Societies of Symbiotic Robot-PlantBio-Hybrids, in *Proceedings of the IEEE Symposium on Artificial Life (IEEE ALIFE'15)*, 2015.

103. Zahadat P., Hamann H., **Schmickl T. (2015)** Evolving Diverse Collective Behaviors Independent of Swarm Density. In: Proceedings of the *Workshop Evolving Collective Behaviors in Robotics, GECCO 2015*, Madrid, Spain, pp. 1245-1246, ACM 2015.
104. Zahadat P., Hamann H., **Schmickl T. (2015)** Evolving Collective Behaviors With Diverse But Predictable Sensor States. In: Proceedings of the *13<sup>th</sup> European Conference on Artificial Life (ECAL 2015)*, York, U.K., pp. 174, MIT Press.
105. **Schmickl T.**, Karsai I. **(2014)** Sting, carry and stock: How corpse availability can regulate de-centralized task allocation in a Ponerine ant colony. *PLoS ONE*, 9(12). doi:10.1371/journal.pone.0114611
106. Salem Z., **Schmickl T. (2014)** The efficiency of the RULES-4 classification learning algorithm in predicting the density of agents. *Cogent Engineering*, 1:986262, doi.org/10.1080/23311916.2014.986262, 986262
107. Hamann H., **Schmickl T.**, Crailsheim K. **(2014)** Analysis of Swarm Behaviors Based on an Inversion of the Fluctuation Theorem. *Artificial Life* 20 (1), 77 - 93.
108. Kimura T., Ohashi M., Crailsheim K., **Schmickl T.**, Okada R., Radspieler G., Ikeno H. **(2014)** Development of a New Method to Track Multiple Honey Bees with Complex Behaviors on a Flat Laboratory Arena. *PLoS ONE*, 9 (1). doi.org/10.1371/journal.pone.0084656, e84656
109. Zahadat P., **Schmickl T. (2014)** Generation of Diversity in a Reaction-Diffusion-Based Controller. *Artificial Life* 20 (3), 319 - 342.
110. Zahadat P., **Schmickl T. (2014)** Wolfpack-inspired Evolutionary Algorithm and a Reaction-Diffusion-based Controller are used for Pattern Formation. Proceedings of Genetic and Evolutionary Computation Conference (*GECCO 2014*), pp. 241-248, ACM 2014.
111. Zahadat P., Bodi M., Salem Z., Bonnet F., de Oliveira M.E., Mondada F., Griparic K., Haus T., Bogdan S., Mills R., Mariano P., Correia L., Kernbach O., Kernbach S. and **Schmickl T. (2014)** Social Adaptation of Robots for Modulating Self-Organization in Animal Societies. In: *Proceedings of SASOW 2014, IEEE Conference on Self-Adaptive and Self-Organizing Systems Workshops (SASOW)*, pp. 55-60, doi:10.1109/SASOW.2014.13.
112. Szopek M., **Schmickl T.**, Thenius R., Radspieler G., Crailsheim K. **(2013)** Dynamics of Collective Decision Making of Honeybees in Complex Temperature Fields. *PloS ONE*, 8(11), doi.org/10.1371/journal.pone.0076250, e76250
113. Halloy J., Mondada F., Kernbach S., **Schmickl T. (2013)** Towards Bio-hybrid Systems Made of Social Animals and Robots In: N.F. Lepora, A. Mura, H. G. Krapp, P. F. M. J. Verschure and T. J. Prescott (eds.): *Living Machines 2013, Lecture Notes in Artificial Intelligence*, LNAI 8064, 384-386.
114. **Schmickl T.**, Bogdan S., Correia L., Kernbach S., Mondada F., Bodi M., Gribovskiy A., Hahshold H., Miklic D., Szopek M., Thenius R., Halloy J. **(2013)**. ASSISI: Mixing Animals with Robots in a Hybrid Society. In: N.F. Lepora et al. (eds.) *Living Machines 2013, Lecture Notes in Artificial Intelligence*, LNAI 8064, 441-443.

115. **Schmickl T.**, Szopek M., Bodi M., Hahshold S., Radspieler G., Thenius R., Bogdan S., Miklic D., Kriparic K., Haus T., Kernbach S., Kernbach, O. (2013) ASSISI: Charged hot bees shakin' in the spotlight, In: Proceedings of the 17<sup>th</sup> IEEE International Conferenceon Self-Adaptive and Self-Organizing Systems, SASO 2013. ISBN 978-0-7695-5129-6. DOI: 10.1109/SASO.2013.26, 259-260
116. Stradner J. , Hamann H., Schwarzer Ch. S.F., Michiels N.K., **Schmickl T.** (2013) Virtual Spatiality in Agent Controllers: Encoding Compartmentalization. In: A.I. Esparcia-Alcázar et al. (eds.) EvoApplications 2013, *Lecture Notes in Computer Science*, LNCS 7835, pp. 579–588.
117. Read M., Möslinger Ch., Dipper T., Kengyel D., Hilder J., Thenius R., Tyrrell A., Timmis J., **Schmickl T.** (2013) Profiling Underwater Swarm Robotic Shoaling Performance using Simulation. In: A. Natraj, S. Cameron, C. Melhuish, M. Witkovski (eds.) Proceedings of the TAROS 2013 conference.
118. Thenius R., Zahadat P., **Schmickl T.** (2013) EMANN - a model of emotions in an artificial neural network. In: Pietro Lió, Orazio Miglino, Giuseppe Nicosia, Stefano Nolfi, Mario Pavone (eds.) *Advances in Artificial Life*, Proceedings of the 12<sup>th</sup> European Conference on the Synthesis and Simulation of Living Systems, ECAL'13. 2<sup>nd</sup>-6<sup>th</sup> September 2013, Taormina, Italy. pp. 830-837.
119. Meister T., Thenius R., Kengyel D., **Schmickl T.** (2013) Cooperation of two different swarms controlled by BEECLUST algorithm. In: Pietro Lió, Orazio Miglino, Giuseppe Nicosia, Stefano Nolfi, Mario Pavone (eds.) *Advances in Artificial Life*, Proceedings of the 12<sup>th</sup> European Conference on the Synthesis and Simulation of Living Systems, ECAL'13. 2<sup>nd</sup>-6<sup>th</sup> September 2013, Taormina, Italy. pp. 1124-1125.
120. Kengyel D., Thenius R., Crailsheim K., **Schmickl T.** (2013) Influence of a Social Gradient on a Swarm of Agents Controlled by the BEECLUST Algorithm. In: Pietro Lió, Orazio Miglino, Giuseppe Nicosia, Stefano Nolfi, Mario Pavone (eds.) *Advances in Artificial Life*, Proceedings of the 12<sup>th</sup> European Conference on the Synthesis and Simulation of Living Systems, ECAL'13. 2<sup>nd</sup>-6<sup>th</sup> September 2013, Taormina, Italy. pp. 1041-1048.
121. Zahadat P., **Schmickl T.**, Crailsheim K. (2013) Evolution of Spatial Pattern Formation by Autonomous Bio-Inspired Cellular Controllers. In: Pietro Lió, Orazio Miglino, Giuseppe Nicosia, Stefano Nolfi, Mario Pavone (eds.) *Advances in Artificial Life*, Proceedings of the 12<sup>th</sup> European Conference on the Synthesis and Simulation of Living Systems, ECAL'13. 2<sup>nd</sup>-6<sup>th</sup> September 2013, Taormina, Italy. pp. 721-728.
122. Zahadat P., Crailsheim K., **Schmickl T.** (2013) Social Inhibition Manages Division of Labour in Artificial Swarm Systems. In: Pietro Lió, Orazio Miglino, Giuseppe Nicosia, Stefano Nolfi, Mario Pavone (eds.) *Advances in Artificial Life*, Proceedings of the 12<sup>th</sup> European Conference on the Synthesis and Simulation of Living Systems, ECAL'13. 2<sup>nd</sup>-6<sup>th</sup> September 2013, Taormina, Italy. pp. 609-616.
123. Scheiner R., Abramson CI., Brodschneider R., Crailsheim K., Farina W.M., Fuchs S., Grünwald B., Hahshold S., Karrer M., Koeniger G., Koeniger N., Menzel R., Mujagic S., Radspieler G., **Schmickl T.**, Schneider C., Siegel A.J., Szopek M., Thenius R. (2013) Standard methods for behavioral studies of *Apis mellifera*., *Journal of Apicultural Research* 52(4): 1-58. DOI 10.3896/IBRA.1.52.4.04. pp. 1-58

124. Hamann H., Karsai I., **Schmickl T.** (2013) Time Delay Implies Cost on Task Switching: A Model to Investigate the Efficiency of Task Partitioning. *Bulletin of Mathematical Biology* 75 (7), 1181-1206. DOI 10.1007/s11538-013-9851-4, pp. 1181-1206
125. Stradner J., Thenius R., Zahadat P., Hamann H., Crailsheim K., **Schmickl T.** (2013) Algorithmic Requirements for Swarm Intelligence in Differently Coupled Collective Systems. *Chaos, Solitons & Fractals* 50(100): 100-114.
126. Thenius R., Bodi M., **Schmickl T.**, Crailsheim K. (2013) Novel method of virtual embryogenesis for structuring Artificial Neural Network controllers. *Mathematical and Computer Modelling of Dynamical Systems* 19(4): 375-387. DOI: 10.1080/13873954.2012.756527
127. Kernbach S., Häbe D., Kernbach O., Thenius R., Radspieler G., Kimura T., **Schmickl T.** (2013) Adaptive collective decision-making in limited robot swarms without communication. *The International Journal of Robotics Research* 32 (1), 35-55.
128. Hamann H., **Schmickl T.**, Crailsheim K. (2012) A Hormone-Based Controller for Evaluation-Minimal Evolution in Decentrally Controlled Systems. *Artificial Life* 18(2), 165-198.
129. Hamann H., **Schmickl T.**, Wörn H., Crailsheim K. (2012) Analysis of Emergent Symmetry Breaking in Collective Decision Making. *Neural Computing and Applications* 21, 207-218. DOI 10.1007/s00521-010-0368-6.
130. **Schmickl T.**, Thenius R., Crailsheim K. (2012) Swarm-intelligent foraging in honeybees: benefits and costs of task-partitioning and environmental fluctuations. *Neural Computing and Applications* 21, 251-268. DOI 10.1007/s00521-010-0357-9.
131. Hamann H., **Schmickl T.**, Crailsheim K. (2012) Self-Organized pattern formation in a Swarm System as a Transient Phenomenon of Non-linear Dynamics. *Mathematical and Computer Modelling of Dynamical Systems* 18, 39-50. DOI: 10.1080/13873954.2011.601418.
132. Zahadat P., **Schmickl T.**, Crailsheim K. (2012) Evolving Reactive Controller for a Modular Robot: Benefits of the Property of State-Switching in Fractal Gene Regulatory Networks. In: "From Animals to Animats 12", *Lecture Notes in Computer Science* 7426, 209-218; DOI: 10.1007/978-3-642-33093-3\_2
133. Hamann H., Stradner J., **Schmickl T.** (2012) Towards Morphological Flexibility: Modular Robotics and Bio-inspired Control. *Proceedings of the Austrian Robotics Workshop* (Operational Programme Slovenia-Austria), Graz, Austria, 2012.
134. Stradner J., Hamann H., Zahadat P., **Schmickl T.**, Crailsheim K. (2012) On-line, On-board Evolution of Reaction-Diffusion Control for Self-Adaptation. *Proceedings of the Alife XIII*, East Lansing, MI, USA, Christoph Adami, David M. Bryson, Charles Ofria, Robert T. Pennock (eds.), pp. 597-598, 2012.
135. Bodi M., Thenius R., **Schmickl T.**, Crailsheim K. (2012) Interaction of robot swarms using the honeybee inspired control algorithm BEECLUST. *Mathematical and Computer Modelling of Dynamical Systems* 18(1): 87-100. DOI: 10.1080/13873954.2011.601420.

136. Knisley J., **Schmickl T.**, Karsai I. (2011) Compartmental Models of Migratory Dynamics. *Mathematical Modelling of Natural Phenomena* 6, pp. 245-259
137. **Schmickl T.**, Hamann H., Crailsheim K. (2011) Modelling a hormone-inspired controller for individual- and multi-modular robotic systems. *Mathematical and Computer Modelling of Dynamical Systems* 17, No. 3, 221–242. DOI: 10.1080/13873954.2011.557862
138. Hamann H., **Schmickl T.**, Crailsheim K. (2011) Explaining Emergent Behavior in a Swarm System Based on an Inversion of the Fluctuation Theorem. In: T. Lenaerts, M. Giacobini, H. Bersini, P. Bourgine, M. Dorigo, R. Doursat (eds.) “Advances in Artificial Life, ECAL 2011: Proceedings of the 11th European Conference on the Synthesis and Simulation of Living Systems. MIT Press pp. 302-309
139. **Schmickl T.**, Stradner J., Hamann H., Winkler L., Crailsheim K. (2011) Major feedbacks that support artificial evolution in multi-modular robotics. *Studies in Computational Intelligence* 341, pp. 195-209
140. **Schmickl T.**, Karsai I. (2011) Regulation of task partitioning by a “common stomach”: a model of nest construction in social wasps. *Behavioral Ecology* 22 (4): 819-830. DOI: 10.1093/beheco/arr060, pp. 819-830
141. Hamann H., **Schmickl T.**, Crailsheim K. (2011) Coupled Inverted Pendulums: A Benchmark for Evolving Decentral Controllers in Modular Robotics. In: N. Krasnogor (eds.) Proceedings of the 13th annual conference on Genetic and evolutionary computation (GECCO 2011). (ACM 978-1-4503-0557-0/11/07), pp. 195-202
142. Bodi M., Thenius R., **Schmickl T.**, Crailsheim K. (2011) How two cooperating robot swarms are affected by two conflictive aggregation spots. In: G. Kampis, I. Karsai, E. Szathmáry (eds.) “Advances in Artificial life – Part II”, *Lecture Notes in Computer Science* 5778, ISBN 978-3-642-21313-7, pp. 367-374
143. Hamann H., **Schmickl T.**, Crailsheim K. (2011) Evolving for Creativity: Maximizing Complexity in a Self-Organized Multi-Particle System. In: G. Kampis, I. Karsai, E. Szathmáry (eds.) “Advances in Artificial life – Part I”, *Lecture Notes in Computer Science* 5777, ISBN 978-3-642-21282-6, pp. 442-349
144. Kengyel D., Schmickl T., Hamann H., Thenius R., Crailsheim K. (2011) Embodiment of Honeybee's Thermotaxis in a Mobile Robot Swarm. In: G. Kampis, I. Karsai, E. Szathmáry (eds.) “Advances in Artificial life – Part II”, *Lecture Notes in Computer Science* 5778, ISBN 978-3-642-21313-7, pp. 69-76
145. Möslinger Ch., **Schmickl T.**, Crailsheim K. (2011) A Minimalist Flocking Algorithm for Swarm Robots. In: G. Kampis, I. Karsai, E. Szathmáry (eds.) “Advances in Artificial life – Part II”, *Lecture Notes in Computer Science* 5778, ISBN 978-3-642-21313-7, pp. 375-382
146. Thenius R., Bodi M., **Schmickl T.**, Crailsheim K. (2011) Growth of Structured Artificial Neural Networks by Virtual Embryogenesis. In: G. Kampis, I. Karsai, E. Szathmáry (eds.) “Advances in Artificial life – Part II”, *Lecture Notes in Computer Science* 5778, ISBN 978-3-642-21313-7, pp. 118-125

147. **Schmickl T.**, Crailsheim K. (2011) Economics of Specialization in Honeybees. A multi-agent simulation study of honeybees. In: G. Kampis, I. Karsai, E. Szathmáry (eds.) “Advances in Artificial life – Part II”, *Lecture Notes in Computer Science* 5778, ISBN 978-3-642-21313-7, pp. 358-366
148. Stradner J., Hamann H., **Schmickl T.**, Thenius R., Crailsheim K. (2011): Evolving a novel bio-inspired controller in reconfigurable robots. In: G. Kampis, I. Karsai, E. Szathmáry (eds.) “Advances in Artificial life – Part I”, *Lecture Notes in Computer Science* 5777, ISBN 978-3-642-21282-6, pp. 132-139
149. **Schmickl T.**, Thenius R., Stradner J., Hamann H., Crailsheim K. (2011) Robotic Organisms - Artificial Homeostatic Hormone System and Virtual Embryogenesis as Examples for Adaptive Reaction-Diffusion Controllers. In: IROS 2011 Workshop–Reconfigurable Modular Robotics: Challenges of Mechatronic and Bio-Chemo-Hybrid Systems. (IROS 2011), organized by Serge Kernbach, Robert Charles Fitch.
150. Hamann H., **Schmickl T.**, Crailsheim K. (2011) Thermodynamics of Emergence: Langton's Ant Meets Boltzmann. In: IEEE (eds.) *Proceedings of the IEEE Symposium on Artificial Life* (2011), pp. 62-69.
151. Thenius R., Dauschan M., **Schmickl T.**, Crailsheim K. (2011) Regenerative abilities in modular robots using virtual embryogenesis. In: A. Bouchachia (eds.) *Proceedings of the International Conference on Adaptive and Intelligent Systems 2011 (ICAIS'11)*, 227-237.
152. Dauschan M., Thenius R., **Schmickl T.**, Crailsheim K. (2011) Using virtual embryogenesis in multi-robot organisms. In: A. Bouchachia (eds.) *Proceedings of the International Conference on Adaptive and Intelligent Systems 2011 (ICAIS'11)*, 238-247.
153. **Schmickl T.**, Thenius R., Möslinger Ch., Halloy J., Campo A., Kernbach S., Dipper T., Sutantyo D., Timmis J., Tyrrell A., Read M., Hilder J., Stefanini C., Manfredi L., Orofino S. (2011) CoCoRo - The Self-aware Underwater Swarm. In: IEEE (eds.) Proceedings of the 5<sup>th</sup> IEEE International Conference on Self-Adaptive and Self-Organizing Systems (SASO 2011) 1<sup>st</sup> Awareness workshop, organized by Emma Hart and Jennifer Willies. DOI: 10.1109/SASOW.2011.11
154. Thenius R., Bodí M., **Schmickl T.**, Crailsheim K. (2010) Using Virtual Embryogenesis for Structuring Controllers. In: E. Hart et al. (eds.) In: E. Hart, C. McEwan, J. Timmis, A. Hone (eds.) Proceedings of the 9<sup>th</sup> International Conference (ICARIS 2010) *Lecture Notes in Computer Science* 6209, 312–313.
155. Hamann H., Stradner J., **Schmickl T.**, Crailsheim K. (2010) Artificial Hormone Reaction Networks: Towards Higher Evolvability in Evolutionary Multi-Modular Robotics. In: Alife (eds.) Proceedings of the 12th International Conference on Artificial Life (*ALife XII*), 773-780.
156. **Schmickl T.**, Hamann H., Stradner J., Mayet R., Crailsheim K. (2010) Complex Taxis-Behaviour in a Novel Bio-Inspired Robot Controller. In: Alife (eds.) Proceedings of the 12th International Conference on Artificial Life (*ALife XII*), 648-655.
157. Kernbach S., **Schmickl T.**, Hamann H., Stradner J., Schwarzer Ch., Schlachter F., Winfield A.F.T., Matthias R. (2010) Adaptive Action Selection Mechanisms for Evolutionary Multimodular Robotics. In: Alife (eds.) Proceedings of the 12th International Conference on Artificial Life (*ALife XII*), 781-788.

158. Mayet R., Roberz J., **Schmickl T.**, Crailsheim K. (2011) Antbots: A feasible visual emulation of pheromone trails for swarm robots. In: M. Dorigo, M. Birattari, G. A. Di Caro, René Doursat, A. P. Engelbrecht, D. Floreano, L. M. Gambardella, R. Groß, E. Şahin, H. Sayama, T. Stützle (eds.) Proceedings of the 7<sup>th</sup> International Conference. *Lecture Notes in Computer Science (LNCS)* 6234, 84-94.
159. Möslinger Ch., **Schmickl T.**, Crailsheim K. (2010) Emergent Flocking with Low-End Swarm Robots. In: Editors (eds.) Proceedings of the 7<sup>th</sup> International Conference. *Lecture Notes in Computer Science (LNCS)* 6234, 424-431.
160. Hamann H., Meyer B., **Schmickl T.**, Crailsheim K. (2010) A Model of Symmetry Breaking in Collective Decisions. In: S. Doncieux and B. Girard and A. Guillot and J. Hallam and J.A. Meyer and J.B. Mouret (eds.) From Animals to Animats XI: Simulation of Adaptive Behavior (SAB'10). *Lecture Notes in Artificial Intelligence (LNAI)* 6226, 639-648.
161. **Schmickl T.** (2010). Bio-Inspiration and Artificial Evolution in Collective Robotics. In: IEEE (eds.) Proceedings of the IEEE International Conference on Robotics and Automation, Anchorage, Alaska, May 3-8, 2010, Workshop on Bio-Inspired Self-Organizing Robotic Systems (*ICRA'2010*).
162. Hamann H., Stradner J., **Schmickl T.**, Crailsheim K. (2010) A Hormone-Based Controller for Evolutionary Multi-Modular Robotics: From Single Modules to Gait Learning. In: IEEE (eds.) Proceedings of the IEEE Congress on Evolutionary Computation *CEC'10*, 244 - 251.
163. **Schmickl T.**, Karsai I. (2010) The interplay of sex ratio, male success and density-independent mortality affects population dynamics. *Ecological Modelling* 221, 1089–1097.
164. **Schmickl T.**, Hamann H., Crailsheim K., Wörn H. (2009) Two Different Approaches to a Macroscopic Model of a Bio-Inspired Robotic Swarm. *Robotics and Autonomous Systems* 57: 913 - 921.
165. Kernbach S., Thenius R., Kernbach O., **Schmickl T.** (2009) Re-embodiment of Honeybee Aggregation Behavior in an Artificial Micro-Robotic System. *Adaptive Behavior* 17(3): 237-256.
166. Corradi P., **Schmickl T.**, Scholz O., Menciassi A., Dario P. (2009) Optical Networking in a Swarm of Microrobots. In: M. Cheng (eds.) Proceedings of the 3<sup>rd</sup> International ICST Conference NanoNet *Lecture Notes of the Institute for Computer Sciences, Social Informatics and Telecommunications Engineering* 3(2): 107 - 119.
167. Stradner J., Hamann H., **Schmickl T.**, Crailsheim K. (2009) Analysis and Implementation of an Artificial Homeostatic Hormone System: A First Case Study in Robotic Hardware. In: IEEE (eds.) Proceedings of the IEEE/RSJ International Conference on Intelligent ROBots and Systems (*IROS'09*), St. Louis, MO, USA, October 11-15, 2009
168. Kernbach S., Hamann H., Stradner J., Thenius R., **Schmickl T.**, van Rossum A.C., Sebag M., Bredeche N., Yao Y., Baele G., Van de Peer Y., Timmis J., Mohktark M., Tyrrell A., Eiben A.E., McKibbin S.P., Liu W., Winfield A.F.T. (2009) On adaptive self-organization in artificial robot organisms. In: Editors (eds.) Proceedings of the First

International Conference on Adaptive and Self-adaptive Systems and Applications (*ADAPTIVE 2009*), Athens/Glyfada, Greece

169. Baele G., Bredeche N., Haasdijk E., Maere S., Michiels N., Van de Peer Y., **Schmickl T.**, Schwarzer Ch., Thenius, R. (2009) Open-ended On-board Evolutionary Robotics for Robot Swarms. In: IEEE (eds.) Proceedings of the IEEE Congress on Evolutionary Computation (*CEC09*) Trondheim, Norway, 18<sup>th</sup> -21<sup>st</sup> of May, 2009, DOI: 10.1109/CEC.2009.4983072
170. Szymanski M., Winkler L., Laneri D., Schlachter F., van Rossum A.C., **Schmickl T.**, Thenius R. (2009) SymbriatorRTOS: A Flexible and Dynamic Framework for Bio-Inspired Robot Control Systems and Evolution. In: IEEE (eds.) Proceedings of the IEEE Congress on Evolutionary Computation (*CEC09*) Trondheim, Norway, 18<sup>th</sup> -21<sup>st</sup> of May, 2009. pp. 3314-3031
171. **Schmickl T.**, Crailsheim K. (2009) Modelling a hormone-based robot controller. In: *ARGESIM Report 35*, 1754 - 1764. In: Mathmod Full Papers CD Volume, I. Troch, F. Breitenecker (eds.) Proceedings MATHMOD 09 Vienna - Full Papers CD Volume, I. Troch, F. Breitenecker, eds., ISBN 978-3-901608-35-3
172. Thenius R., **Schmickl T.**, Crailsheim K. (2009) Novel concept of modelling embryology for structuring an artificial neural network. In: Mathmod Full Papers CD Volume, I. Troch, F. Breitenecker (eds.) *ARGESIM Report 35*, 1821 - 1828. Proceedings MATHMOD 09 Vienna., ISBN 978-3-901608-35-3
173. Radspieler G., Thenius R., **Schmickl T.** (2009) Individual-based modelling of temperature-induced aggregation behaviour. In: Mathmod Full Papers CD Volume, I. Troch, F. Breitenecker (eds.) *ARGESIM Report 35*, 895 - 903. Proceedings MATHMOD 09 Vienna - Full Papers CD Volume, ISBN 978-3-901608-35-3
174. Bodi M., Thenius R., **Schmickl T.**, Crailsheim K. (2009) Robustness of two interacting robot swarms using the BEECLUST algorithm. In: Mathmod Full Papers CD Volume, I. Troch, F. Breitenecker (eds.) *ARGESIM Report 35*, 904 - 912. Proceedings MATHMOD 09 Vienna - Full Papers CD Volume, ISBN 978-3-901608-35-3
175. **Schmickl T.**, Crailsheim K. (2008) Analysing honeybees' division of labour in broodcare by a multi-agent model. In: Bullock, S., Noble, J., Watson, R., Bedau, M. A. (eds.) *Artificial Life XI*: Proceedings of the Eleventh International Conference on the Simulation and Synthesis of Living Systems. MIT Press, Cambridge, MA: 529-536.
176. Kernbach S., Meister E., Schlachter F., Jebens K., Szymanski M., Liedke J., Laneri D., Winkler L., **Schmickl T.**, Thenius R., Corradi P., Ricotti L. (2008) Symbiotic Robot Organisms: Replicator and Symbriion Projects. In: PerMIS (eds.) Symbiotic Robot Organisms: Replicator and Symbriion Projects. Proceedings of the *PerMIS 08*, August 19-21, 2008, Gaithersburg, MD, USA pp. 62-69
177. Hamann H., Wörn H., Crailsheim K., **Schmickl T.** (2008) Spatial Macroscopic Models of a Bio-Inspired Robotic Swarm Algorithm. In: IEEE (eds.) Proceedings of the IEEE/RSJ International Conference on Intelligent Robots and Systems, *IROS'08*, Nice, 2008. pp. 1415-1420
178. **Schmickl T.**, Crailsheim K. (2008) An individual-based model of task selection in honeybees. In: M. Asada, J. C. T. Hallam, J.-A. Meyer, J. Tani (eds.) Proceedings of the

- 10<sup>th</sup> International Conference on Simulation of Adaptive Behavior (SAB 2008). *Lecture Notes in Computer Science* 5040: 383-392.
179. Thenius R., **Schmickl T.**, Crailsheim K. (2008) Optimisation of a honeybee-colony's energetics via social learning based on queuing delays. *Connection Science* 20 (2-3): 193-210.
180. **Schmickl T.**, Thenius R., Möslinger Ch., Radspieler G., Kernbach S., Szymanski M., Crailsheim K. (2008) Get in touch: cooperative decision making based on robot-to-robot collisions. *Autonomous Agents and Multi-Agent Systems* 18(1): 133-155.
181. **Schmickl T.**, Crailsheim K. (2008) Trophallaxis within a robot swarm: Bio-inspired communication among robots in a swarm. *Autonomous Robots* 25: 171-188.
182. **Schmickl T.**, Crailsheim K. (2008) TaskSelSim: A Model of the Self-Organisation of the Division of Labour of Honeybees. *Mathematical and Computer Modelling of Dynamical Systems* 14: 101 – 125.
183. **Schmickl T.**, Möslinger Ch., Thenius R., Crailsheim K. (2007) Individual adaptation allows collective path-finding in a robotic swarm. *International Journal of Factory Automation, Robotics and Soft Computing* 4: 102 – 108.
184. **Schmickl T.**, Möslinger C., Thenius R., Crailsheim K. (2007) Bio-inspired Navigation of Autonomous Robots in Heterogenous Environments. *International Journal of Factory Automation, Robotics and Soft Computing* 3: 164 – 170. ISSN 1828-6984.
185. **Schmickl T.**, Crailsheim K. (2007) HoPoMo: A model of honeybee intracolonial population dynamics and resource management. *Ecological Modelling* 204: 219 – 245.
186. **Schmickl T.**, Crailsheim K. (2007) A Navigation Algorithm for Swarm Robotics Inspired by Slime Mold Aggregation. In: Sahin E., Spears W.M., Winfield A.F.T. (eds.). *Swarm Robotics; Second SAB 2006 International Workshop*. *Lecture Notes in Computer Science* 4433: 1 – 13.
187. **Schmickl T.**, Möslinger, C., Crailsheim K. (2007) Collective perception in a robot swarm. In: Sahin E., Spears W.M., Winfield A.F.T. (eds.). *Swarm Robotics; Second SAB 2006 International Workshop*. *Lecture Notes in Computer Science* 4433: 144 – 157.
188. Valdastri P., Corradi P., Menciassi A., **Schmickl T.**, Crailsheim K., Seyfried S., Dario P. (2006) Micromanipulation, Communication and Swarm Intelligence Issues in a Swarm Microrobotic Platform. *Robotics and Autonomous Systems* 54: 789-804.
189. **Schmickl T.**, Crailsheim K. (2006) Bubbleworld.evo: Artificial evolution of behavioral decisions in a simulated predator-prey ecosystem. In: Nolfi, S., Baldassarre, G., Calabretta, R., Hallam, J.C.T., Marocco, D., Meyer, J.-A., Miglino, O., Parisi, D. (eds.) *From Animal to Animats 9 (SAB 2006)*, *Lecture Notes in Artificial Intelligence* 4095, pp. 594-605, Springer Verlag Berlin Heidelberg.
190. Thenius R., **Schmickl T.**, Crailsheim K. (2006) Economic optimisation in honeybees: adaptive behaviour of a superorganism. In: Nolfi, S., Baldassarre, G., Calabretta, R., Hallam, J.C.T., Marocco, D., Meyer, J.-A., Miglino, O., Parisi, D. (eds.) *From Animal to Animats 9 (SAB 2006)*, *Lecture Notes in Artificial Intelligence* 4095, pp. 725-737, Springer Verlag Berlin Heidelberg.

191. **Schmickl T.**, Crailsheim K. (2006) Trophallaxis among swarm-robots: A biologically inspired strategy for swarm robotics. In: IEEE (eds.) Proceedings of the 1<sup>st</sup> IEE/RAS-EMBS International Conference on Biomedical Robotics and Biomechanotronics (*BIOROB 2006*). 20.2.-22.2.2006, Pisa, Italy. ISBN 1-4244-0040-6, IEEE-Catalog-No: 06EX1254D.
192. **Schmickl T.**, Crailsheim K. (2006) Modelling the self-organized division of labour in honeybees. In: Mathmod (eds.) Proceedings of the 5<sup>th</sup> Vienna Symposium on Mathematical Modelling (MATHMOD), 8.2.-10.2.2006, Vienna. *ARGESIM Report* No. 30, eds. I.Troch, F.Breitenecker. ISBN 3-901608-3.
193. Thenius R., **Schmickl T.**, Crailsheim K. (2006) Modelling nectar-collecting behaviour in a honeybee colony. In: Mathmod (eds.) Proceedings of the 5<sup>th</sup> Vienna Symposium on Mathematical Modelling (MATHMOD), 8.2.-10.2.2006, Vienna. *ARGESIM Report* No. 30, eds. I.Troch, F.Breitenecker. ISBN 3-901608-3.
194. Thenius R., **Schmickl T.**, Crailsheim K. (2005) The “Dance or Work” Problem: Why Do not all Honeybees Dance with Maximum Intensity. In: M. Pechoucek, P. Petta, and L.Z. Varga (eds.) Proceedings of the 4th International Central and Eastern European Conference on Multi-Agent Systems, (CEEMAS 2005) *Lecture Notes in Artificial Intelligence* (LNAI) 3690, pp. 246–255, 2005. Springer-Verlag Berlin Heidelberg.
195. **Schmickl T.**, Thenius R., Crailsheim K. (2005) Simulating Swarm Intelligence in Honey Bees: Foraging in Differently Fluctuating Environments In: GECCO (eds.) Proceedings of the Genetic and Evolutionary Computation Conference (*GECCO 2005*), June 25-29, 2005, Washington, DC, USA. (ACM 1-59593-010-8/05/0006). pp. 273-274
196. **Schmickl T.**, Crailsheim K. (2004) Costs of environmental fluctuations and benefits of dynamic decentralized foraging decisions in honey bees. *Adaptive Behavior* 12: 263-277.
197. **Schmickl T.**, Crailsheim K. (2004) Inner nest homeostasis in a changing environment with special emphasis on honeybee brood nursing and pollen supply. *Apidologie* 35: 249-263.
198. **Schmickl T.**, Crailsheim K. (2003) Costs of environmental fluctuations and benefits of dynamic decentralized foraging decisions in honey bees. In: MASI (eds.) Proceedings of the 2nd International Workshop on the Mathematics and Algorithms of Social Insects (*MASI 2003*), Georgia Institute of Technology, Atlanta, GA 30332, December 15-17, 2003. pp. 145-152
199. **Schmickl T.**, Crailsheim K. (2003) A honeybee population model with special emphasis on resource management and division of labor. In: IMACS (eds.) Proceedings of the 4th IMACS Symposium on Mathematical Modelling, Feb. 5-7, 2003, Vienna, Austria, *ARGESIM Report* No. 24, ISBN 3-901608-24-9.
200. **Schmickl T.**, Blaschon B., Gurmann B., Crailsheim K. (2003) Collective and individual nursing investment in the queen and in young and old honeybee larvae during foraging and non-foraging periods. *Insectes Sociaux* 50: 174–184.
201. **Schmickl T.**, Crailsheim K. (2002) How honeybees (*Apis mellifera* L.) change their broodcare behavior in response to non-foraging conditions and poor pollen conditions. *Behavioral Ecology Sociobiology* 51: 415–425.

202. **Schmickl T.**, Crailsheim K. (2001) Cannibalism and early capping: Strategy of honeybee colonies in times of experimental pollen shortages. *Journal of Comparative Physiology* 187: 541–547.
203. Möse J.R., Miorini T., **Schmickl T.** (1994) Zur Problematik der Schimmelpilz-Sporenkonzentration in der Luft von Krankenhäusern. *Krankenhaus-Hygiene und Infektionsverhütung* 16: 162-167. ("The problem of mould spores in the air of hospitals").

**Articles in books and book chapters (peer-reviewed<sup>(\*)</sup> or editor-reviewed<sup>(+)</sup>):**

1. Ilgün A., Angelov K., **Schmickl T.** (2024) 'Fostering Symbiosis in the Eusocial Realm: The State of the Mycelial Hive Design in HIVEOPOLIS'. In: Driving Design Vol II, edited by Distributed Design, 288-301. <sup>(+)</sup>
2. Vogrin, M., Szopek, M., Becher, M., Stefanec, M., Lazic, D., Stokanic, V., Hofstadler, D.N., Fedotoff, L., **Schmickl, T.** (2024) Biohybride Technologien zur Unterstützung von Natur und Mensch. In: M. Tamborini (ed.) Die Philosophie der Bio-Robotik. Felix Meiner Verlag. <sup>(+)</sup>
3. Ilgun, A., Szopek, M., **Schmickl, T.** (2024) The Eusocial Cathedral and the Bazaar: A Novel Synthesis from De- and Reconstructing the Living and the Artificial. In: The Cultures of Entanglement - On Nonhuman Life Forms in Contemporary Art. Suzanne Anker & Sabine Flach (eds.). pp. 327-354. Transcript Verlag. <sup>(+)</sup>
4. Ilgün, A., Mills, R., Mondada, F., **Schmickl, T.** (2022) A study model for reconstructing urban ecological niches. In: *Structures and Architecture. A Viable Urban Perspective?*: Proceedings of the Fifth International Conference on Structures and Architecture (ICSA 2022), July 6-8, 2022, Aalborg, Denmark, pg. 75-82. ISBN: 9781003023555<sup>(\*)</sup>
5. Ilgün, A., Mondada, F., Mills, R., **Schmickl, T.** (2022) A Study Model for the Reconstruction of Urban Ecological Niches. *Proceedings of the Fifth International Conference on Structures and Architecture (ICSA 2022)*, July 6-8, 2022, Aalborg, Denmark, vol 2, pg. 27-34. ISBN 9780367902810<sup>(\*)</sup>
6. Szopek, M., Thenius, R., Stefanec, M., Hofstadler, D.N., Varughese, J.Ch., Vogrin, M., Radspieler, G., **Schmickl, T.** (2021). Autonome Roboterschwärme als Stabilisatoren gefährdeter Ökosysteme. In: *Navigationen - Zeitschrift für Medien- und Kulturwissenschaften*, 21(1), 149-180. <sup>(+)</sup>
7. **Schmickl, T.**, Szopek, M., Radspieler, G., Bodi, M., Schönwetter-Fuchs, S., Salem, Z., Stefanec, M., Thenius, R., Hahshold, S. (2020). Virtual Animal Studies/Hybrid Societies. In *Handbuch Virtualität* (pp. 629-651). Springer VS, Wiesbaden. <sup>(+)</sup>
8. Karsai I., **Schmickl T.** (2020) Social Stomach. In: Starr C. (eds) *Encyclopedia of Social Insects*. Springer, Cham. DOI: 10.1007/978-3-319-90306-4\_111-1<sup>(\*)</sup>
9. Hamann, H., Von Mammen, S., Mauser, I., Ayres, P., Banzhaff, W., Bentley, P., Dittrich, P., Dorigo, M., Doursat, R., Hensen, J., Höhl, W., Jacob, C., Menges, A., Michel, O., Napp, N., Petersen, K., Sayama, H., **Schmickl, T.**, Stoy, K., Theraulaz, G., Werfel, J., Zamuda, A. (2019) In: *Proceedings-2018 IEEE 3rd International Workshops*

*on Foundations and Applications of Self\* Systems, FAS\* W 2018, SOCO 2018 Foreword: 2nd International Workshop on Self-Organised Construction.* pp XIX<sup>(\*)</sup>

10. **Schmickl, T.**, Müggenburg, J., Warnke, M. (2018) Perverse Bienen. Artificial Life und der Apfel der Erkenntnis. *Zeitschrift für Medienwissenschaft*, 10 (1), 98-110.<sup>(+)</sup>
11. Scheiner R., Abramson C.I., Brodschneider R., Crailsheim K., Farina W., Fuchs S., Grünewald B., Hahshold S., Karrer M., Koeniger G., Koeniger N., Menzel R., Mujagic S., Radspieler G., **Schmickl T.**, Schneider C., Siegel A.J., Szopek M., Thenius R. (2013) Standard methods for behavioural studies of *Apis mellifera*. In: V Dietemann; J D Ellis; P Neumann (eds.) *The COLOSS BEEBOOK, Volume I: standard methods for Apis mellifera research*. DOI: 10.3896/IBRA.1.52.4.04<sup>(\*)</sup>
12. **Schmickl T.**, Crailsheim K., Deneubourg J.-L., Halloy J. (2013) Bio-mimetic and bio-inspired design of collective systems. In: S. Kernbach, P. Levy (eds.) *Handbook of Collective Robotics: Fundamentals and Challenges*, Springer.<sup>(\*)</sup>
13. Winfield A.F.T., Kernbach S., **Schmickl T.** (2013) Collective foraging: Cleaning, energy harvesting and trophallaxis. In: S. Kernbach, P. Levy (eds.) *Handbook of Collective Robotics: Fundamentals and Challenges*, Springer.<sup>(\*)</sup>
14. **Schmickl T.**, Crailsheim K. (2012) Modelling Population dynamics, division of labour and nutrient economics of social insect colonies. In: *Ecological Modeling*. Wen-Jun Zhang (eds.). Nova Science Publishers, Inc., NY, USA. Pp. 223-265. ISBN: 978-1-61324-567-5.<sup>(+)</sup>
15. **Schmickl T.** (2011) How to engineer robotic organisms and swarms? Bio-inspiration, bio-mimicry, and artificial evolution in embodied self-organized systems. In: Yan Meng and Yaochu Jin (eds.) *Bio-Inspired Self-Organizing Robotic Systems. Studies in Computational Intelligence* Volume 355, 2011, DOI: 10.1007/978-3-642-20760-0. pp. 25-52.<sup>(+)</sup>
16. **Schmickl T.**, Hamann H. (2011) BEECLUST: A Swarm Algorithm Derived from Honeybees. Derivation of the Algorithm, Analysis by Mathematical Models and Implementation on a Robot Swarm. In: Yang Xiao, Dr. Fei Hu (eds.), *Bio-inspired Computing and Communication Networks*, Auerbach Publications, CRC Press. pp. 95-138.<sup>(+)</sup>
17. **Schmickl T.**, Hamann H., Stradner J., Crailsheim K. (2010): Hormone-based Control for Multi-modular Robotics. In: P. Levi and S. Kernbach (eds.): *Symbiotic Multi-Robot Organisms: Reliability, Adaptability, Evolution*. Springer.<sup>(\*)</sup>
18. Thenius R., Bodi M., **Schmickl T.**, Crailsheim K. (2010): Evolving Artificial Neural Networks and Artificial Embryology. In: P. Levi, S. Kernbach (Eds.) *Symbiotic Multi-Robot Organisms: Reliability, Adaptability, Evolution*. Springer.<sup>(\*)</sup>
19. **Schmickl T.** (2009) Schwarmintelligenz am Beispiel der Ameisenstraßen. In: Denisia 25: „Geschätzt, verflucht, allgegenwärtig Ameisen in Biologie und Volkskultur“. pp. 188. ISSN: 1608-8700.<sup>(+)</sup>
20. **Schmickl T.**, Möslinger Ch., Thenius R., Crailsheim K. (2008) Individual adaptation allows collective path-finding in a robotic swarm. In: S. Pennachio (eds.) *Recent advances in Control Systems, Robotics and Automation*, ISBN: 978-88-901928-3-8,

International Society for Advanced Research, www.internationalsar.org. pp. 217 – 222.<sup>(\*)</sup>

21. **Schmickl T.**, Möslinger C., Thenius R., Crailsheim K. (2007) Bio-inspired Navigation of Autonomous Robots in Heterogenous Environments. In: S. Pennachio (eds.) *Emerging Technologies, Robotics and Control Systems*, Vol. 2, International Society for Advanced Research, www.internationalsar.org. pp. 126 – 132.<sup>(\*)</sup>
22. **Schmickl T. (2003)** Sammeln, Verteilen und Bewerten von Informationen: Verteilte Intelligenz in einem Bienenvolk. In: *FACTS 1: Die Informationsgesellschaft* (eds. Gesellschaft zur Durchführung von Fachhochschulstudiengängen St. Pölten), Böhlau Verlag, Wien, Köln, Weimar. ISBN 3-205-77183-4. pp. 103–120. ("Collecting, distributing and assessment of information: distributed intelligence in a honeybee colony").<sup>(+)</sup>

### **Scientific preprint papers (not reviewed):**

1. **Schmickl, T. (2022)**. Strong Emergence Arising from Weak Emergence. <https://doi.org/10.48550/arXiv.2202.00431>
2. **Schmickl T.**, Stefanec M. (2019) A Primordial Particle System in three dimensions. <https://arxiv.org/abs/1901.09293>
3. Hornischer H., Varughese J.C., Thenius R., Wotawa F., Füllsack M., **Schmickl T. (2019)** CIMAX: Collective Information Maximization in Robotic Swarms Using Local Communication. <https://arxiv.org/abs/1903.05444>
4. Wahby, M., Heinrich, M.K., Hofstadler, D.N., Zahadat, P., Risi, S., Ayres, P., **Schmickl, T.**, Hamann H. (2018) A Robot to Shape your Natural Plant: The Machine Learning Approach to Model and Control Bio-Hybrid Systems. <https://doi.org/10.48550/arXiv.1804.06682>
5. Hofstadler, D.N., Varughese, J.C., Nielsen, S.A., Leon, D.A., Ayres, P., Zahadat, P., **Schmickl, T. (2018)** Artificial Plants - Vascular Morphogenesis Controller-guided growth of braided structures. <https://doi.org/10.48550/arXiv.1804.06343>
6. Varughese, J.C., Hornischer, H., Thenius, R., Zahadat, P., Wotawa, F., **Schmickl, T. (2018)** Controlling Swarms: A Programming Paradigm with Minimalistic Communication. <https://doi.org/10.48550/arXiv.1804.04202>
7. Hamann, H., Soorati, M.D., Heinrich, M.K., Hofstadler, D.N., Kuksin, I., Veenstra, F., Wahby, M., Nielsen, S.A., Risi, S., Skrzypczak, T., Zahadat, P., Wojtaszek, P., Støy, K., **Schmickl, T.**, Kernbach, S., Ayres, P. (2017) Flora robotica -- An Architectural System Combining Living Natural Plants and Distributed Robots. <https://doi.org/10.48550/arXiv.1709.04291>
8. **Schmickl, T.**, Zahadat, P., Hamann, H. (2016) Sooner than Expected: Hitting the Wall of Complexity in Evolution. <https://doi.org/10.48550/arXiv.1609.07722>
9. **Schmickl, T.**, Stefanec, M. (2015) Population Dynamics of Self-Replicating Cell-like Structures Emerging from Chaos. <https://doi.org/10.48550/arXiv.1512.04478>

10. Kernbach, S., **Schmickl, T.**, Timmis, J. (2010) Collective Adaptive Systems: Challenges Beyond Evolvability. <https://doi.org/10.48550/arXiv.1108.5643>
11. Hamann, H., Stradner, J., **Schmickl, T.**, Crailsheim, K. (2010) Artificial Hormone Reaction Networks: Towards Higher Evolvability in Evolutionary Multi-Modular Robotics. <https://doi.org/10.48550/arXiv.1011.3912>

### **Short workshop papers (editor reviewed):**

1. **Schmickl T.**, Thenius R., Timmis J., Tyrrell A., Halloy J., Stefanini C., Manfredi L., Campo A., Sutantyo D., Kernbach S. (2011) CoCoRo: A swarm of self-aware underwater robots. In: IEEE (eds.) Proceedings of the 5<sup>th</sup> IEEE Conference (ICAR 2011) – workshop “underwater robotics”, organized by Maarja Kruusmaa, Giovanni Indiveri and Gianluca Antonelli, DOI: 10.1109/SASOW.2011.11
2. **Schmickl T.**, Thenius R., Timmis J., Tyrrell A., Halloy J., Stefanini C., Manfredi L., Campo A., Sutantyo D., Kernbach S. (2011) CoCoRo: The self-aware swarm of underwater robots. In: IEEE (eds.) Proceedings of the 5<sup>th</sup> IEEE Conference (IROS 2011) - IEEE/RSJ International Conference on Intelligent Robots and Systems. Workshop “Redundancy in Robot Manipulators and Multi-Robot Systems”, organized by Dejan Milutinovic, Jacob Rosen.

### **Articles in popular scientific journals (editor reviewed):**

1. Zahadat P., **Schmickl T.** (2016) Division of Labor in a Swarm of Autonomous Underwater Robots by Improved Partitioning Social Inhibition. *Adaptive Behavior* 24(2), 87-101
2. Radspieler G., Thenius R., Szopek M., Hahshold S., **Schmickl T.**, Crailsheim K. (2012) Vibration als Ersatz für soziale Stimuli bei jungen Honigbienen. *Entomologica Austriaca* 19, 66-68.
3. **Schmickl T.**, Möslinger Ch., Thenius R. (2011) A self-aware swarm of underwater vehicles. *AWARENESS magazine*. DOI 10.2417/3201111.003880.
4. Thenius R., Bodi M., **Schmickl T.**, Crailsheim K. (2010) Evolving virtual embryogenesis to structure complex controllers. *PerAda magazine*, DOI 10.2417/2201009.003291, 368–371
5. Hahshold S., Radspieler G., Szopek M., Thenius R., **Schmickl T.**, Crailsheim K. (2010) Robuste Gruppenentscheidungen bei Honigbienen, in: *Entomologica Austriaca* 17, 125 - 126.
6. **Schmickl T.**, Thenius R. Möslinger Ch., Crailsheim K. (2009) Bio-Inspiration als Weg zu intelligenten Roboterschwärmen. *Entomologica Austriaca* 16, 154-155.
7. Szopek M., Radspieler G., Thenius R., **Schmickl T.**, Crailsheim K. (2009). Verhalten junger Honigbienen in zweidimensionalen Temperaturgradienten. *Entomologica Austriaca* 16, 151-152.

8. **Schmickl T.**, Thenius R., Crailsheim K. (2006) Kollektive Sammelentscheidungen: eine Multi-Agenten-Simulation einer Honigbienenkolonie. *Entomologica Austriaca* 13, 15-24. ISSN 1681-0406.
9. Thenius R., **Schmickl T.**, Crailsheim K. (2006) Einfluß der Individualität bei Sammelbienen (*Apis mellifera L*) auf den Sammelerfolg. *Entomologica Austriaca* 13, 25-29. ISSN 1681-0406.
10. **Schmickl T. (2005)** Mathematische Modellierung der Populationsdynamik eines Bienenvolkes. *Entomologica Austriaca* 12, 6-12, ISSN 1681-0406.
11. Crailsheim K., Thenius R., **Schmickl T. (2004)** Ottimizzazione della raccolta del nettare nelle api. *APOidea* 1: 5-11. ISSN 1724-8167. ("Optimisation of nectar foraging in honeybees").
12. Crailsheim K., **Schmickl T. (2002)** Was fressen Bienen bei schlechtem Wetter? *Deutsches Bienen Journal* 7: 4-6. ISSN 0943-2914. ("What do honeybees eat in times of bad weather?").
13. **Schmickl T.**, Crailsheim K. (2001) Brutkannibalismus bei Honigbienen (*Apis mellifera carnica*) - Wie Honigbienen die Größe ihres Brutnestes bei längeren Schlechtwetterperioden regulieren. *Entomologica Austriaca* 2, 10-11.

### ***Invited papers, position papers, editorials (editor reviewed):***

1. Romano, D., Porfiri, M., Zahadat, P., **Schmickl, T. (2024)**. Animal–robot interaction—an emerging field at the intersection of biology and robotics. *Bioinspiration & Biomimetics*, 19(2), 020201
2. **Schmickl, T. (2023)** Die Honigbiene: Eine Bestäubungsheldin. Magazin „Die Münze“ 1. Ausgabe 2023, 34th year edition. (pp.14-17) Publisher: „Münze Österreich“. This article accompanied a special silver coin with a honeybee waggle dance theme, in honor Prof. Karl v. Frisch.
3. **Schmickl, T.**, Stefanec, M., Hofstadler, D.N., Krajnik, T., Turgut, A.E., Arvin, F. (2021) The Queen and her Robotic Court: A Minimally-Invasive Form of Ecosystem Hacking. Proceedings of the The 5th Annual Science Fiction Prototyping Conference (SciFi-It'2021), Philippe Geril and Monika Polańska (eds.) EUROSIS-ETI.
4. **Schmickl T. (2011)** Unmasking 5 common rumors on artificial collective adaptive systems. Position paper at: Consultation workshop "living technology / artificial systems / embodied evolution", 10<sup>th</sup> Nov. in Brussels (FET Proactive).
5. Halloy J., Kernbach S., **Schmickl T. (2011)** Towards mixed societies of animals and robots. Position paper at: Consultation workshop "living technology / artificial systems / embodied evolution", 10<sup>th</sup> Nov. in Brussels (FET Proactive).
6. Hamann H., **Schmickl T. (2011)** Modelling the swarm: Analysing biological and engineered swarm systems. Editorial of the special issue “Modelling the Swarm” in Mathematical and Computer Modelling of Dynamical Systems, 2011, Taylor & Francis. DOI: 10.1080/13873954.2011.601426.

7. Kernbach S., **Schmickl T.**, Timmis J. (2009) Collective Adaptive Systems: Challenges Beyond Evolvability. Position paper at the FET external consultation “Fundamentals of collective adaptive systems”, Brussels, 3<sup>rd</sup>-4<sup>th</sup> Nov. 2009.
8. **Schmickl T.**, Kernbach S. (2009): Creating adaptive systems that are as “rich” as their natural counterparts? Challenges for Evolvability. Position paper at the FET external consultation “Fundamentals of collective adaptive systems”, Brussels, 3<sup>rd</sup>-4<sup>th</sup> Nov. 2009.

### **Abstracts, short papers and letters in peer-reviewed journals:**

1. Zahadat P., Hamann H., **Schmickl T.** (2015) Evolving Diverse Collective Behaviors Independent of Swarm Density, In: Companion Publication of the 2015 Annual Conference on Genetic and Evolutionary Computation (GECCO Companion '15), GECCO 2015, Sara Silva (Ed.). ACM, New York, NY, USA, 1245-1246.
2. Zahadat P., Hamann H., **Schmickl T.** (2015): Evolving Collective Behaviors With Diverse But Predictable Sensor States. Proceedings of the 13<sup>th</sup> European conference on Artificial Life (ECAL 2015), York, UK, 2015 (2015)
3. Szopek M., Hahshold S., Thenius R., Bodi M., Crailsheim K., **Schmickl T.** (2014) ASSISIbf: Honeybees and robots form a bio-hybrid society. *Entomologica Austriaca* 21, 242-243.
4. Szopek M., Hahshold S., Thenius R., **Schmickl T.**, Crailsheim K., (2012) How social cues influence collective decisions in honeybees. *Apidologie* 42, 786-787.
5. Hahshold S., Radspieler G., Thenius R., **Schmickl T.**, Crailsheim K. (2010) Cooperative thermotaxis in honeybees: social gradient vs. temperature gradient. *Apidologie* 41, 686-687.
6. Szopek M., Radspieler G., Thenius R., **Schmickl T.**, Crailsheim K. (2010) Cooperative thermotaxis in honeybees: flexible group behaviour in a dynamic environment. *Apidologie* 41, pp. 687.
7. Radspieler G., Szopek M., Hahshold S., Thenius R., **Schmickl T.**, CrailsheimK. (2010) Analysis of honeybee locomotion behaviour. *Apidologie* 41, pp. 686.
8. Szopek M., Radspieler G., Thenius R., **Schmickl T.**, Crailsheim K. (2009) Cooperative thermotaxis in honeybees: Group decisions in a complex temperature gradient. *Apidologie* 40, pp. 663
9. Szopek M., Radspieler G., Thenius R., **Schmickl T.**, Crailsheim K. (2009). Verhalten junger Honigbienen in zweidimensionalen Temperaturgradienten. *Entomologica Austriaca* 16 , 154-155
10. Hahshold S., Radspieler G., Thenius R., **Schmickl T.**, Crailsheim K. (2009) Cooperative thermotaxis in honeybees: How robust are group decisions? *Apidologie* 40, pp. 51 - 670

11. Vollmann J., Thenius R., **Schmickl T.**, Crailsheim K. (2009) Contact-free age determination of honeybee larvae (*Apis mellifera*). *Apidologie* 40, pp. 662
12. Thenius, R., **Schmickl, T.**, Crailsheim, K. (2008) How to know without having been there? Investigating communication channels in the nectar collecting system of a honeybee colony. In: Bullock, S., Noble, J., Watson, R., Bedau, M. A. (eds.) Artificial Life XI: Proceedings of the Eleventh International Conference on the Simulation and Synthesis of Living Systems. MIT Press, Cambridge, MA: pp.807
13. Vollmann J., **Schmickl T.**, Crailsheim K. (2004) The reaction of honeybee colonies to different quantities of brood. *Apidologie* 35: 546-547.
14. Thenius R., **Schmickl T.**, Crailsheim K. (2004) Multi-factorial simulation of the nectar income dynamics in honeybee colonies. *Apidologie* 35: 545-546.
15. Hergouth M., Petz M., **Schmickl T.**, Crailsheim K. (2004) Minimised structural complexity of honeybee colonies. *Apidologie* 35: 544-545.
16. Hrassnigg N., Brodschneider R., Riessberger-Galle U., **Schmickl T.**, Danzer M., Stabentheiner A., Crailsheim K. (2001) Observations on the grooming behaviour of worker bees (*Apis mellifera*). *Apidologie* 32: 502-503.
17. **Schmickl T.**, Crailsheim K. (2001) Survival of honeybee larvae in times of pollen stress. *Apidologie* 32: 496-498.
18. Hrassnigg N., Loidl A., Riessberger U., **Schmickl T.**, Danzer M., Stabentheiner A., Crailsheim K. (2000) Observations on the hygienic behaviour of honeybee workers (*Apis mellifera L.*). *Apidologie* 31: 649-650.
19. **Schmickl T.**, Crailsheim K. (2000) Nursing of honeybees depending on weather, resources and other hive conditions (*Apis mellifera L.*). *Apidologie* 31: 642-644.
20. **Schmickl T.**, Crailsheim K. (1998) The influence of weather conditions on brood nursing by honeybees (*Apis mellifera L.*). *Apidologie* 29: 460-462.

### ***Abstracts in citable conference proceedings (editor reviewed):***

1. Vollmann J., Thenius R., **Schmickl T.** (2019) Novel method for multiple parameter analyses of suboptimal brood conditions in honeybee colonies - Fast, simple and easy to handle -. Für die 66. Jahrestagung der Arbeitsgemeinschaft der Institute für Bienenforschung, Goethe-Universität, Otte-Stern-Zentrum am Uni Campus Riedberg, Frankfurt am Main (26.-28. März 2019).
2. Hahshold, S., Ploder, R., Radspieler, G., Szopek, M., **Schmickl, T.**, Crailsheim, K. (2016) Behaviour of single young honeybees and groups of young honeybees in a temperature gradient. In: EUROIUSSI (Hg.): EUROIUSSI Abstract book
3. Szopek, M., Hahshold, S., Thenius, R., Bodi, M., Crailsheim, K., **Schmickl, T.** (2014) ASSISIbf: Honeybees and robots form a bio-hybrid society. Entomologica Austriaca 21 (OEG Tagung Abstracts).

4. Szopek, M., Bodi, M., Hahshold, S., Thenius, R., **Schmickl, T. (2014)** ASSISIbf: A new pathway to examine collective behaviours in honeybees. In: IUSSI (Hg.): Abstract Book of the XVII IUSSI International Congress (Cairns, Australia).
5. Szopek, M., Hahshold, S., Thenius, R., Bodi, M., **Schmickl, T.**, CrailsheimK. (2013) The path to ASSISI|bf: How honeybees and machines can make collective decisions. 60. AG Tagung der deutschsprachigen Bieneninstitute, Würzburg, Germany.
6. Hahshold S., Szopek M., Radspieler G., Thenius R., **Schmickl T.**, Crailsheim K.: (2012) *Collective decision making in honeybees: temperature gradient vs social gradient*. In: (Hg.): Abstracts for the 5<sup>th</sup> Congress of the European Sections of International Union for the Study of Social Insects, Montecatini Terme, Italy.
7. Szopek, M., Bodi, M., Radspieler, G., **Schmickl, T.**, Crailsheim, K (2012) Modelling collective decision making in honeybees. Eurbee 2012, Halle (Saale), Germany.
8. Kengyel D., Radspieler G., Wotawa F., **Schmickl T. (2012)**: OR: *Emulation of collective honeybee behaviour by a swarm of simple robot*, für: 5th Congress of the European Sections of the International Union for the Study of Social Insects, Montecatini Terme, Italy.
9. Hahshold S., Szopek M., Radspieler G., Thenius R., **Schmickl T.**, Crailsheim K. (2010) Collective Decision making in honeybees: environmental attraction factors versus socially driven aggregation. In: David R. Nash Susanne P.A. den Boer Henrik H. De Fine Licht Jacobus J. Boomsma (eds.): Abstracts for the XVI Congress of the International Union for the Study of Social Insects (*IUSSI'10*) Copenhagen, Denmark, 8-13 August 2010.
10. **Schmickl T.**, Radspieler G., Szopek M., Hahshold S., Thenius R., Wissekal D., Crailsheim K. (2010) From honeybee behaviour to swarm robotics. In: David R. Nash Susanne P.A. den Boer Henrik H. De Fine Licht Jacobus J. Boomsma (eds.): Abstracts for the XVI Congress of the International Union for the Study of Social Insects (*IUSSI'10*) Copenhagen, Denmark, 8-13 August 2010.
11. Szopek M., Radspieler G., Thenius R., **Schmickl T.**, Crailsheim K. (2010) Cooperative thermotaxis of honeybees in a complex and dynamic thermal environment. In: David R. Nash Susanne P.A. den Boer Henrik H. De Fine Licht Jacobus J. Boomsma (eds.): Abstracts for the XVI Congress of the International Union for the Study of Social Insects (*IUSSI'10*) Copenhagen, Denmark, 8-13 August 2010.
12. Szopek M., Radspieler G., **Schmickl T.**, Thenius R., Crailsheim, K. (2008) PO: Recording and tracking of locomotion and clustering behaviour in young honeybees (*Apis mellifera*), Measuring Behavior 2008.
13. **Schmickl T.**, Thenius R., Crailsheim K. (2005) Collective decision making: A multi-agent simulation of a foraging honeybee colony. In: Bees, Ants and Termites: Applied and Fundamental Research, edited by: HH Kaatz, M Becher and RFA Moritz, IUSSI International Union zum Studium der Sozialen Insekten. Halle/Saale, Germany. ISBN 3-901864-02-4. pp. 138.
14. Thenius R., **Schmickl T.**, Crailsheim K. (2005) Importance of heterogeneity in honeybee (*Apis mellifera L.*) dance-response curves for optimal foraging. In: Bees, Ants and Termites: Applied and Fundamental Research, edited by: HH Kaatz, M

- Becher and RFA Moritz, IUSSI International Union zum Studium der Sozialen Insekten. Halle/Saale, Germany. ISBN 3-901864-02-4. pp. 140.
15. **Schmickl T.**, Crailsheim K. (2005) A mathematical model for predicting intra-colonial population dynamics of honeybees. In: Bees, Ants and Termites: Applied and Fundamental Research, edited by: HH Kaatz, M Becher and RFA Moritz, IUSSI International Union zum Studium der Sozialen Insekten. Halle/Saale, Germany. ISBN 3-901864-02-4. pp. 60.
  16. **Schmickl T.**, Crailsheim K. (2004) Analyzing the efficiency of honeybee foraging decisions by multi-agent simulation. In: Proceedings of the First European Conference of Apidology (EURBEE'04). 19<sup>th</sup>-24<sup>th</sup> September 2004, Udine, Italy, edited by I. Bernardelli and N. Milani, Arti Grafiche Friulane SpA, Udine, ISBN 88-86550-99-5, pp. 52.
  17. Petz M., **Schmickl T.**, Crailsheim K. (2004) Simulating the adaptation of nursing to changes of colony supply to brood ratio. In: Proceedings of the First European Conference of Apidology (EURBEE'04). 19<sup>th</sup>-24<sup>th</sup> September 2004, Udine, Italy, edited by I. Bernardelli and N. Milani, Arti Grafiche Friulane SpA, Udine, ISBN 88-86550-99-5, pp. 53-54.
  18. Brodschneider R., **Schmickl T.**, Crailsheim K. (2004) Individual nurse bees' behaviour in changing nursing workloads. In: Proceedings of the First European Conference of Apidology (EURBEE'04). 19<sup>th</sup>-24<sup>th</sup> September 2004, Udine, Italy, edited by I. Bernardelli and N. Milani, Arti Grafiche Friulane SpA, Udine, ISBN 88-86550-99-5, pp. 54.
  19. Vollmann J., Hrassnigg N., **Schmickl T.**, Crailsheim K. (2004) Regulation of nursing workforce in a honeybee colony according to different workloads. In: Proceedings of the First European Conference of Apidology (EURBEE'04). 19<sup>th</sup>-24<sup>th</sup> September 2004, Udine, Italy, edited by I. Bernardelli and N. Milani, Arti Grafiche Friulane SpA, Udine, ISBN 88-86550-99-5, pp. 55.
  20. Hergouth M., **Schmickl T.**, Crailsheim K. (2004) Efficiency of brood care behaviour in dwarf colonies. In: Proceedings of the First European Conference of Apidology (EURBEE'04). 19<sup>th</sup>-24<sup>th</sup> September 2004, Udine, Italy, edited by I. Bernardelli and N. Milani, Arti Grafiche Friulane SpA, Udine, ISBN 88-86550-99-5, pp. 55-56.
  21. Thenius R., **Schmickl T.**, Crailsheim K. (2004) Formation of multiple transfers in honeybee forager-receiver interaction, a multi-agent simulation. In: Proceedings of the First European Conference of Apidology (EURBEE'04). 19<sup>th</sup>-24<sup>th</sup> September 2004, Udine, Italy, edited by I. Bernardelli and N. Milani, Arti Grafiche Friulane SpA, Udine, ISBN 88-86550-99-5, pp. 55-56.
  22. **Schmickl T.**, Crailsheim K. (2001) SimBee: Simulating population dynamics and pollen management of a honeybee colony. Proceedings of the IUSSI'2001, Berlin, Germany.
  23. **Schmickl T.**, Crailsheim K. (2001) SimBee: Population and resource dynamics of a honeybee colony. Symposium "From the worker to the colony" by the British section of IUSSI, Dez. 2001 in Cambridge, UK.

***Participated Conferences, Symposia, Workshops and Exhibits as presenter, panelist or (co-)author of presentations, posters or demonstrators:***

**2025:** IEEE Applied Sensing Conference, India (1 contribution).

**2024:** IEEE Robosoft 2024, San Diego, USA (1 contribution); COLIBRI Focus workshop, Graz, AT (7 contributions); BioRob 2024 conference, Heidelberg, DE (3 contributions); AQUA 2024 conference, Copenhagen, DK (2 contributions); Complexity of Life conference, Graz, AT (2 contributions); Cladocers 2024 conference, Verbania, IT (2 contributions); DZG Tagung 2024, Stuttgart, DE (1 contribution); IEEE CASE 2024 conference, Bari, IT (1 contribution); IEEE MARSS 2024 conference, Delft, NL (1 contribution), IEEE CCTA, Newcastle, UK (1 contribution).

**2023:** ALIFE conference 2023, Sapporo, Japan (2 contributions, online); BioBienenApfel Event 2023, Vienna, Austria (1 contribution); Conference on Biomimetic and Biohybrid Systems, Genua, Italy, (1 contribution); IEEE International Conference on Mechatronics, Loughborough , UK (1 contribution); 2<sup>nd</sup> International Conference on Robotics, Automation and Artificial Intelligence (RAAI), Singapore (1 contribution); ICRA 2023, London, UK (1 contribution); COLIBRI Doc Day, Graz, Austria (1 contribution), MOFA – Molluskenforschung Österreich, Lunz am See, Austria (1 contribution), German Zoological Society (DZG), Kassel, Germany (2 contributions).

**2022:** ALIFE conference 2022, Trento, Italy (3 contributions, online); BioBienenApfel Event in Spielberg, Austria (1 contribution); BioBienenApfel Kickoff Event, Munich, Germany (1 contribution); Brain, Behavior & Society Springschool (2 contributions); “Digital Future of Bees”, Limerick, Ireland (1 contribution); IROS, 2022; Kyoto, Japan (2 contributions); ICSA2022, Aalborg, Denmark (1 contribution); Lange Nacht der Forschung, Graz, Austria (1 contributions, online); 31<sup>st</sup> International Conference on Robotics in Alpe-Adria-Danube Region, Klagenfurt, Austria (1 contribution); I.N.S.E.C.T. Summer School, Newcastle, U.K. (1 contribution, presence) and Hvalso Denmark (1 contribution, online); SIL - Austrian Limnological Association conference, Illmitz, Austria (2 contributions); 7<sup>th</sup> Research Symposium of the Nationalparks, Vienna, Austria (1 contribution); ACA Züchtertagung 2022, St. Johann im Pongau, Austria (1 contribution).

**2021:** ALIFE conference 2021, Prague, Czech Republic (3 contributions, online); “STEIERMARK SCHAU“ at the Kunsthaus Graz (2 contributions), Austria; pre-COP26 conference 2021, Pontedera, Italy (1 contribution); “Biohybrid Systems” at Purdue University, U.S.A. (1 contribution); SCIFI-IT 2021, Ghent, Belgium (1 contribution); “Beyond AI” Virtual Vehicle Cluster summer school, Graz, Austria (2 contributions, online); GUSEGG 2021, virtual event (1 contribution, online); Mycology for Architecture Symposium, virtual event (1 contribution, online); Lecture at the Academy of Fine Arts and Design Bratislava (1 contribution, online).

**2020:** IROS 2020, Las Vegas, USA (1 contribution, online); IEEE SSCI ALIFE 2020, Cranberra, Australia (2 contributions, online); xCoAx conference, Graz, Austria (1 contribution, online); GreenTech Cluster Innovators Club Event, Graz, Austria (1 contribution, online); EU Future Tech Week, Brussels, Belgium (1 contribution, online); Podium discussion “Nachhaltige Entwicklung”, Graz, Austria (1 contribution); EU Future Tech Week (EU-EIC), Brussels, Belgium (2 contributions).

**2019:** Ars Electronica 2019, Linz, Austria (2 contributions); Kapelica Gallery – Artificial Life Symposium, Ljubljana, Slovenia (2 contributions); Workshop-subCULTron, Venice, Italy (1 contribution); EU European Innovation Days, Brussels, Belgium (2 contributions); Workshop Hiveopolis, Berlin, Germany (5 contributions); ALIFE 2019, Newcastle, U.K. (3 contributions); Vienna Design Week, Vienna, Austria (2 contributions); Vienna Maker Faire, Vienna, Austria (1 contribution); Respond Festival, Copenhagen, Denmark (2 contributions), Naturally Hypernatural V, Graz, Austria (1 contribution); 3<sup>rd</sup> Global BioSummit at MIT Media Lab, Boston, USA (2 contributions).

**2018:** ICTP 2018, Triest, Italy (1 contribution); Ars Electronica 2018, Linz, Austria (1 contribution); "SCIENTIĆ & ROBOTICA", Lausanne, Schweiz (1 contribution); EU ICT 2018 fair, Vienna, Austria (1 contribution).

**2017:** 4th Faculty of Biology AMU Conference-2017, Wasaw, Poland (1 contribution); IEEE ALIFE 2017, Honolulu, U.S.A (3 contributions); Lakeside Days, Klagenfurt, Austria (1 contribution); Bienentage 2017, Graz Austria (1 contribution); subCULTron Arsenale event, Venice, Italy (1 contribution); Assisi\_bf Summer School 2017, Graz, Austria (2 contributions).

**2016:** Workshop “Berechnete Tiere. Technik und Verdatung in den Human-Animal-Studies” 2016, Bochum, Germany (2 contributions); CAMS 2016, Trondheim, Norway (1 contribution); Ars Electronica 2016, Linz, Austria (1 contribution); Assisi\_bf Winter School 2016, Lausanne, Switzerland (2 contributions).

**2015:** MATHMOD 2015, Vienna, Austria (2 contributions); EVOSTAR 2015, Kopenhagen, Denmark (1 contribution); ECAL 2015, York, U.K. (2 contributions); DZG 2015, Graz, Austria (6 contributions); PRIMA 2015, Bertinoro, Italy (1 contribution); EXPO 2015, Mestre, Italy (1 contribution); IROS 2015, Hamburg, Germany (1 contribution).

**2014:** SASO 2014, London, UK (1 contribution); GECCO 2014, Vancouver, Canada (1 contribution); EVOSTAR 2014, Granada, Spain (1 contribution); IUSSI 2014, Cairns, Australia (1 contribution); ÖEG-Koloquium 2014, Graz, Austria (2 contributions); Symposium on Biomathematics and Ecology: Education and Research 2014, Claremont, CA, U.S.A (1 contribution); CEBIT 2014, Hannover, Germany (1 contribution); Living Machines, Milano, Italy (1 contribution); TEDxGraz, Graz, Austria (2 contributions).

**2013:** TAROS 2013, Oxford, U.K. (1 contribution); ECAL 2013, Taormino, Italy (5 contributions); Living Machines 2013 (2 contributions) London, U.K. (2 contributions); SASO 2013, Philadelphia, U.S.A. (1 contribution); Apimondia, Kiev, Ukraine (2 contributions); German Bee Research Seminar, Würzburg, Germany (2 contributions).

**2012:** EurBee 2012, Halle an der Saale (3 contributions); IUSSI 2012, Montecatini Terme, Tuscany, Italy (3 contributions); German Bee Research Seminar, Bonn, Germany (2 contributions), SAB, Odense, Denmark (1 contribution).

**2011:** SSCI'11, Paris, France (1 contribution); FET Conference, Budapest, Hungary (1 contribution); GECCO'11, Dublin, Ireland (1 contribution); ICAR'11, Tallinn, Estonia (1 contribution); IROS'11, San-Francisco, U.S.A (2 contributions); SASO'11, Ann Arbor, USA (1 contribution); ICAIS'11, Klagenfurt, Austria; BIONETICS 2011, York, U.K. (1 contribution).

**2010:** ICRA'10, Anchorage, U.S.A (1 contribution); CEC'10, Barcelona, Spain (1 contribution); ANTS'10, Brussels, Belgium (2 contributions); Alife XII, Odense, Denmark (3

contribution); IUSSI 2010, Copenhagen, Denmark (5 contributions); SAB'10, Paris, France (1 contribution); RESEARCH 2010, Graz, Austria (1 contribution).

**2009:** German Bee Research Seminar, Schwerin, Germany (3 contributions); APIMONDIA Montpellier, France (2 contributions); OEG Kolloquium, Graz, Austria (2 contributions); IROS, St. Luis U.S.A (2 contributions); ADAPTIVE 2009, Athens, Greece (1 contribution); IUSSI 2009 Fraueninsel Chiemsee, Germany (3 contributions); ECAL 2009, Budapest, Hungary (7 contributions); MATHMOD, Vienna, Austria (5 contributions); IEEE Congress on Evolutionary Computation (CEC'09), Trondheim, Norway (2 contributions).

**2008:** Measuring Behavior 2008, Maastricht, Netherlands (1 contribution); 4<sup>th</sup> European Meeting of the IUSSI (IUSSI'08), La Roche-en Ardenne, Belgium (2 contributions); 3rd European Conference of Apidology (EURBEE'08), Belfast, Northern Ireland (1 contribution); Workshop on Modelling Complex Biological Systems, Uppsala, Sweden (1 contribution); Simulating Artificial Behaviour, Osaka, Japan (1 contribution); Artificial Life XI, Winchester, U.K. (2 contributions); PerMis 08, Gaithersburg, USA (1 contribution); International Conference on Intelligent Robots and Systems, Nice, France (1 contribution); International Conference on Nano-Networks, Boston, U.S.A (1 contribution)

**2007:** Quantitative Biology Curriculum Planning Workshop, Johnson City, USA (participation); MathFest, San Jose, U.S.A (1 contribution); IUSSI, Bochum, Germany (2 contributions)

**2006:** MATHMOD, Vienna, Austria (2 contributions); SAB Conference, Rome, Italy (2 contributions); SAB workshop on swarm robotics, Rome, Italy (2 contributions); BIOROB, Pisa, Italy (1 contribution); EURON, Palermo, Italy (participation); EUROBEE, Prague, Czech Republic (1 contribution); IUSSI Washington, U.S.A (1 contribution)

**2005:** IUSSI, Halle, Germany (3 contributions); GECCO, Washington, USA (1 contribution); CEEMAS, Budapest, Hungary (1 contribution); EURON, Warszaw, Poland (1 workshop); CEQUACOS, Graz, Austria (1 contribution); IUSSI, St. Petersburg, Russia (2 contributions); OEG/ESA Colloquium, St. Pölten, Austria (2 contributions); EURON, Warsaw, Poland (1 workshop contribution); APIMONDIA, Dublin, Ireland (1 contribution)

**2004:** EURBEE, Udine, Italy (6 contributions); OEG/ESA Expert talk, Graz, Austria (1 contribution); German Bee Research Seminar, Münster, Germany (3 contributions)

**2003:** IUSSI, Regensburg, Germany (1 contribution); MASi, Atlanta, U.S.A (1 contribution); MATHMOD, Vienna, Austria (1 contribution); European Forum Alpbach (participation)

**2002:** CEQUACOS, Graz, Austria (1 contribution); Bienentag, Lunz, Austria (1 contribution); European Forum Alpbach (participation).

**2001:** German Bee Research Seminar, Bad Neuenahr, Germany (2 contributions); IUSSI, Cambridge, U.K. (1 contribution); IUSSI, Berlin, Germany (1 contribution)

**2000:** German Bee Research Seminar, Blaubeuren, Germany (2 contributions); OEG/ESA Expert talk, Vienna, Austria (1 contribution)

**1999:** APIMONDIA, Vancouver, Canada (1 contribution)

**1998:** German Bee Research Seminar, Bremen, Germany (1 contribution)